

biohaviour

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# GEOMETRIC CHALLENGES FOR THE BLIND WATCHMAKER



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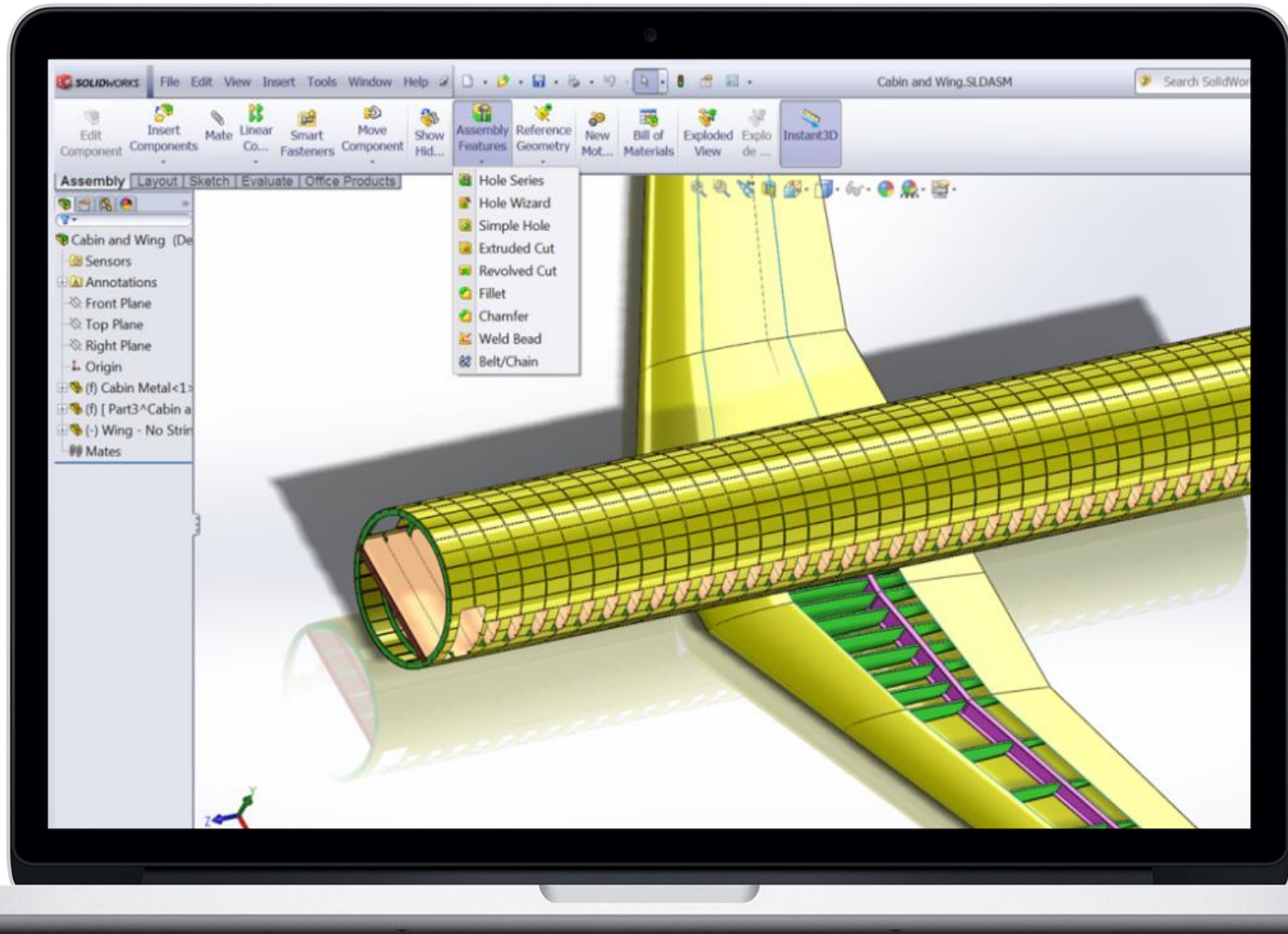


# BIO-INSPIRED GENERATIVE DESIGN SYSTEMS

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- Inspiration
- Investigations
- Implementation







## ORDER FROM CHAOS

Simple Rules - Extraordinary Results.

3 Rules for Flocking:

1. \_\_\_\_\_

# SEPARATION

avoid crowding neighbours (short range repulsion)



## ORDER FROM CHAOS

Simple Rules - Extraordinary Results.  
3 Rules for Flocking:

2. \_\_\_\_\_

# ALIGNMENT

steer towards average heading of neighbours





## ORDER FROM CHAOS

Simple Rules - Extraordinary Results.

3 Rules for Flocking:

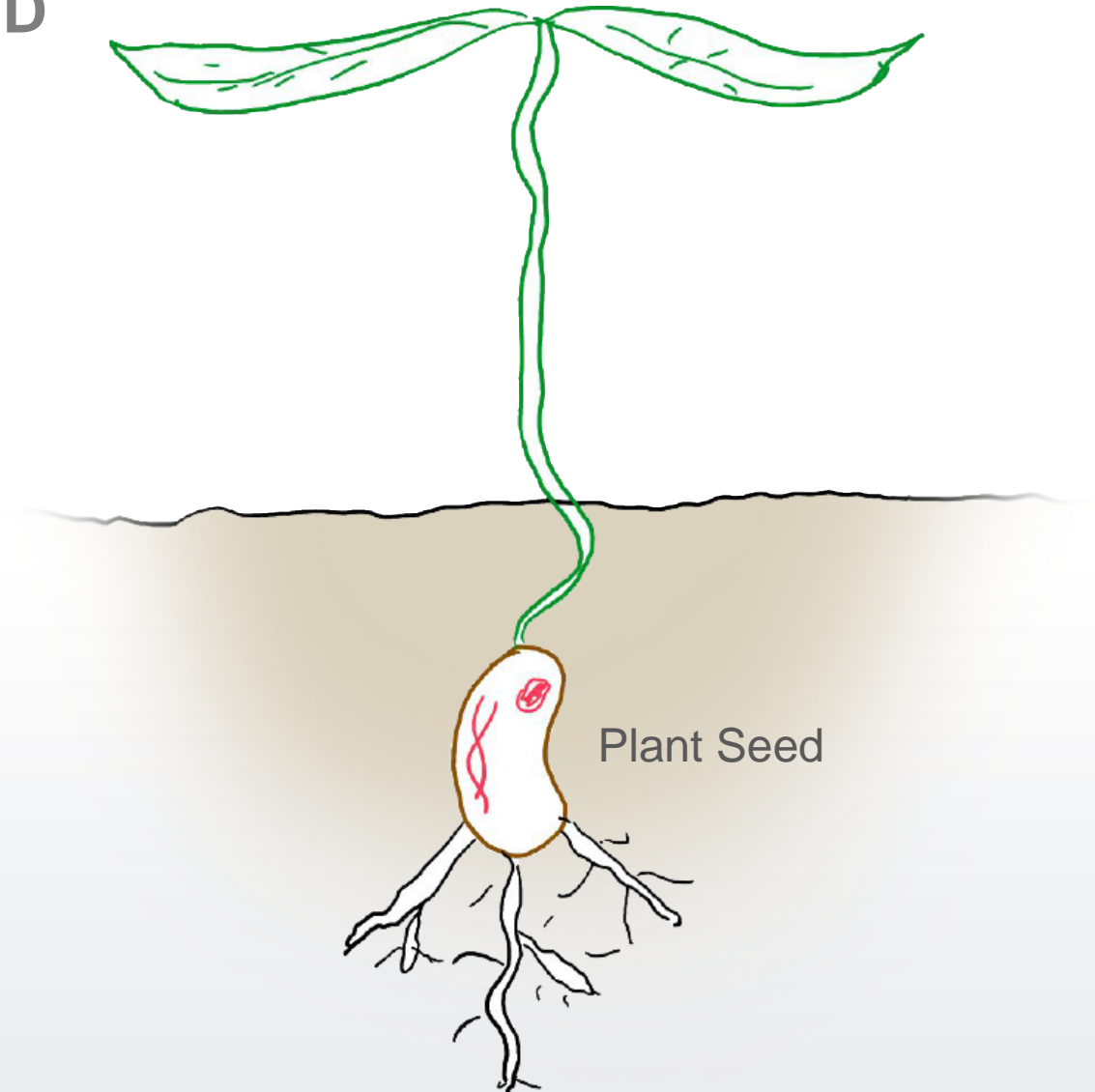
3 \_\_\_\_\_

# COHESION

steer towards average position of neighbours  
(long range attraction)



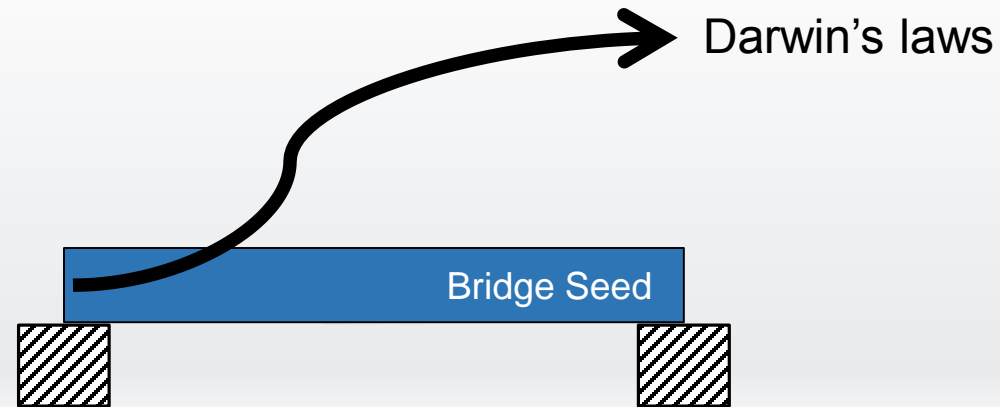
## BIO-INSPIRED







## BIO-INSPIRED



$$F=ma$$

$$[F] = [K][d]$$

$$\sum_{i=1}^n \sum_{k=1}^m f_{i,j} = 0$$

Newton's 3 laws



## ETHOS

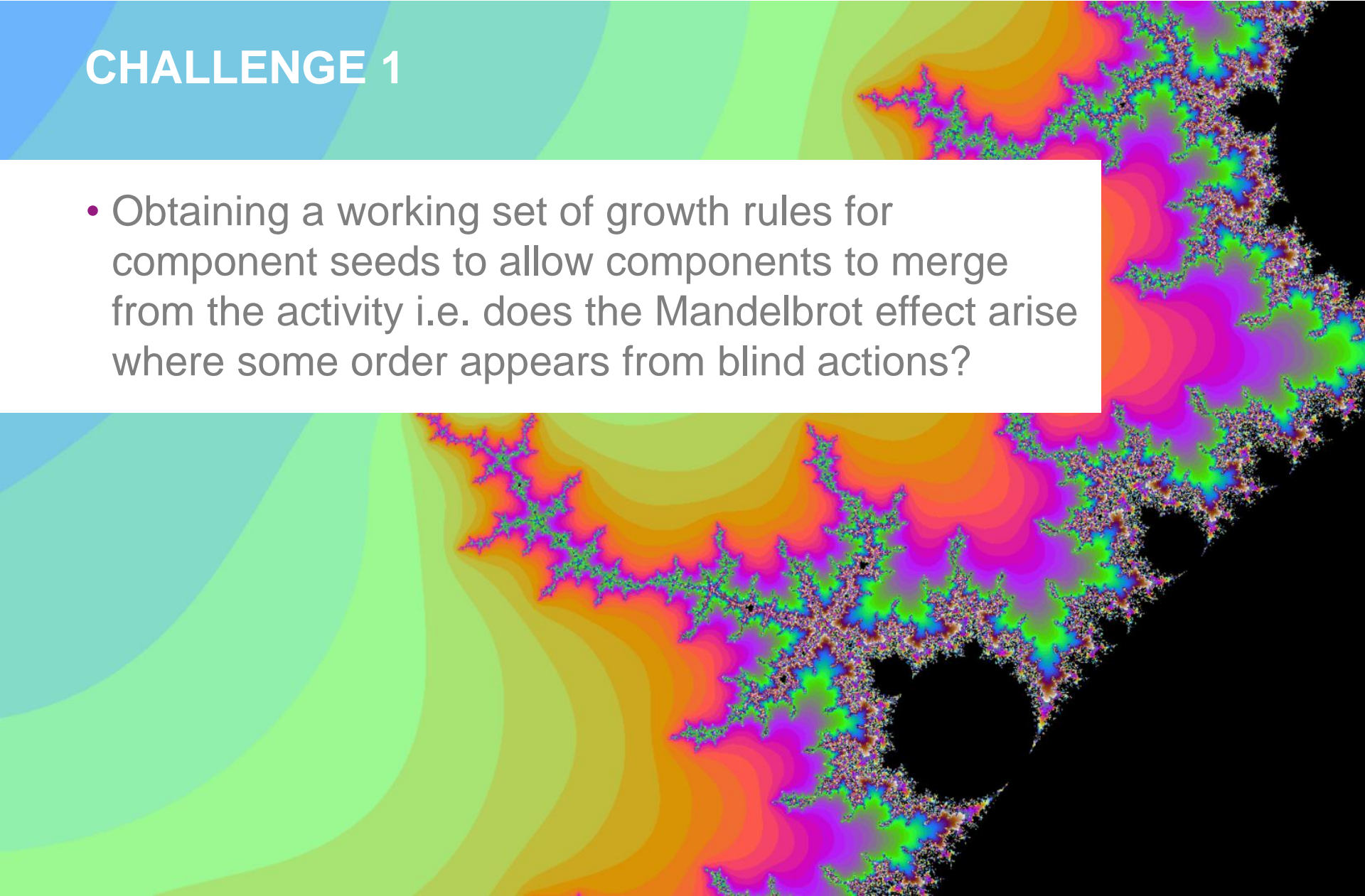
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- Rethink design rules and processes
- Create a new autonomous design process
- Radically change roles and activities in the manufacturing organisation
- Embrace emergent behaviour for design innovation



## CHALLENGE 1

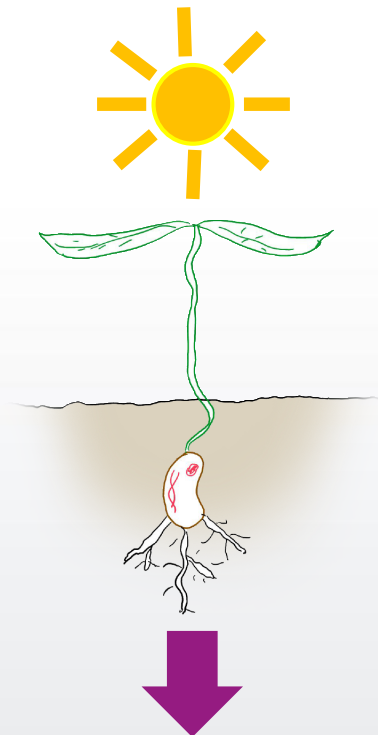
- Obtaining a working set of growth rules for component seeds to allow components to merge from the activity i.e. does the Mandelbrot effect arise where some order appears from blind actions?





## CHALLENGE 2

- **Defining stimuli** that will make the component seeds grow and establishing if that growth can be controlled via the stimuli.



GRAVITY?

STRESS?

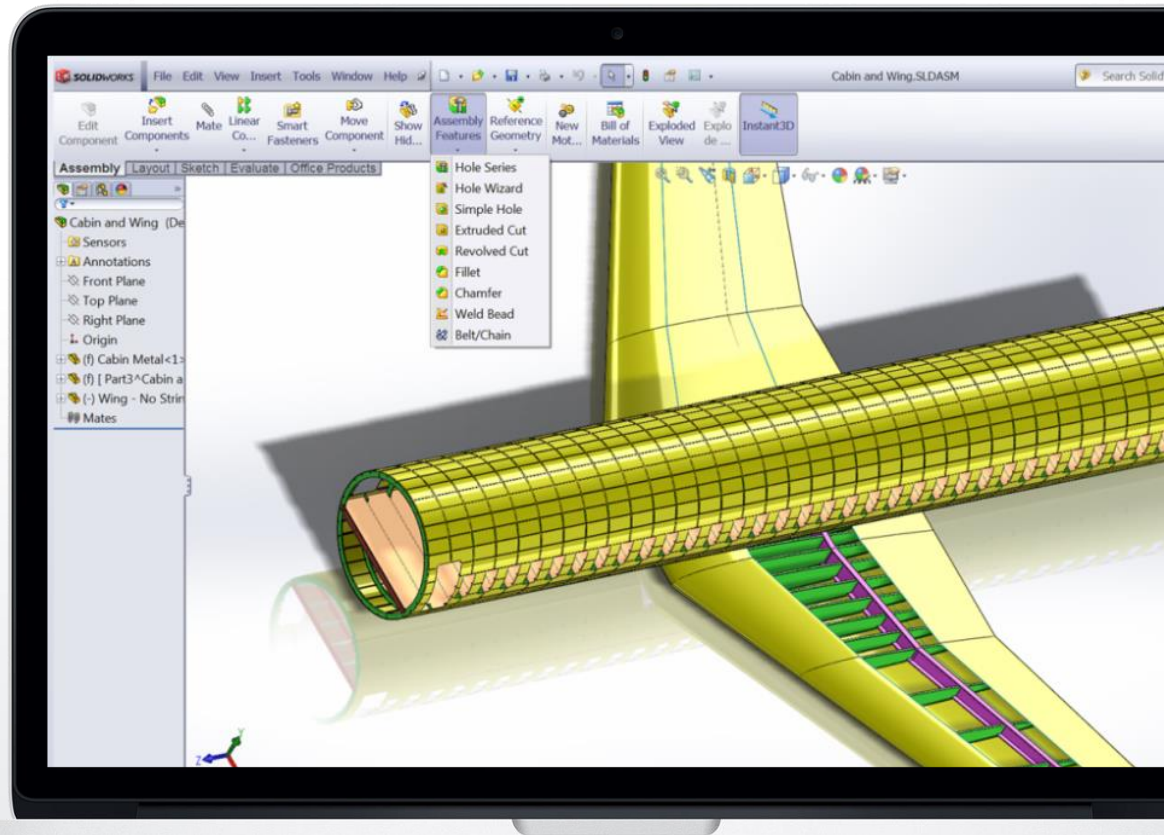
COST?

ENERGY?



## CHALLENGE 3

- Capturing emergent behaviour into a working set of parameters that can interact with existing design & manufacturing systems - i.e. is there a set of parameters which will define a CAD model?



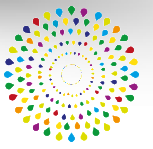


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## PROGRESS SUMMARY

- AGENTS
- INTEGRATED SYSTEMS
- INVESTIGATIONS





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# AGENTS



## AGENTS

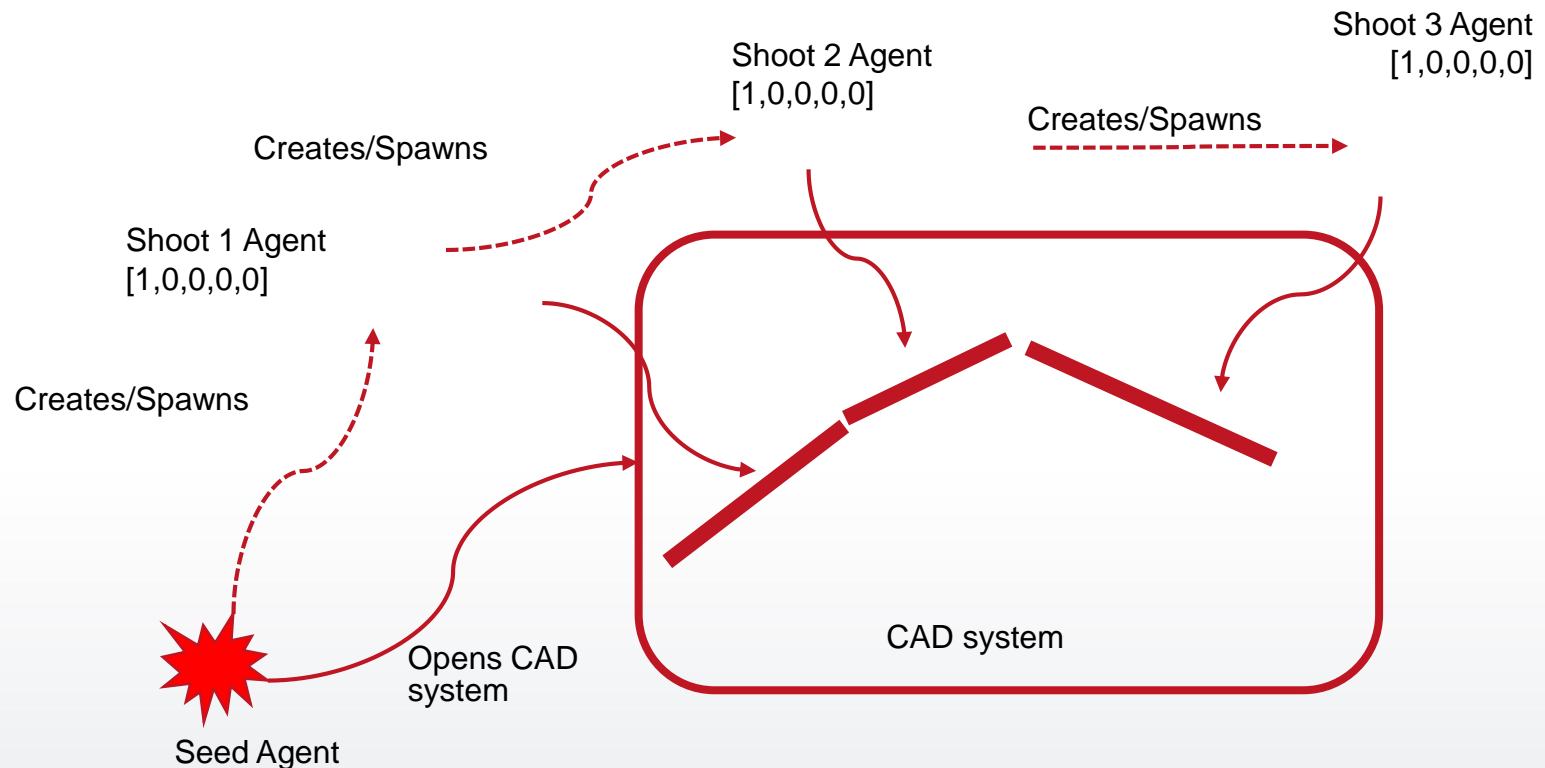
- Agent has:
  - (i) A Belief set: what the agent believes to be true
  - (ii) An Event: describes an occurrence in response to which the agent must take action
  - (iii) A Plan: the instructions the agent follows to try to achieve its goals and handle its designated events, and
  - (iv) A Capability: the functional components that make up an agent to be aggregated and reused





## AGENTS

- Agents linked to CAD entities
  - Each agent represents a CAD entity line



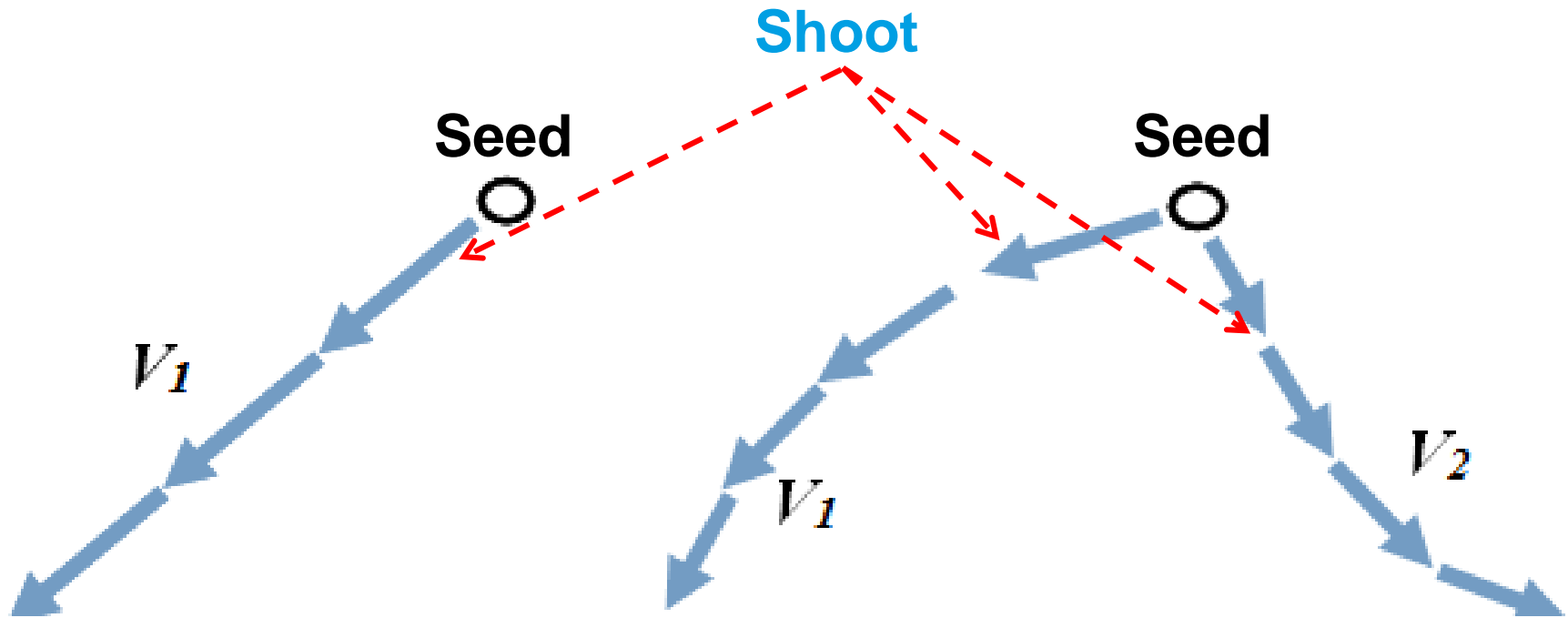


## WHAT IS A GENE?

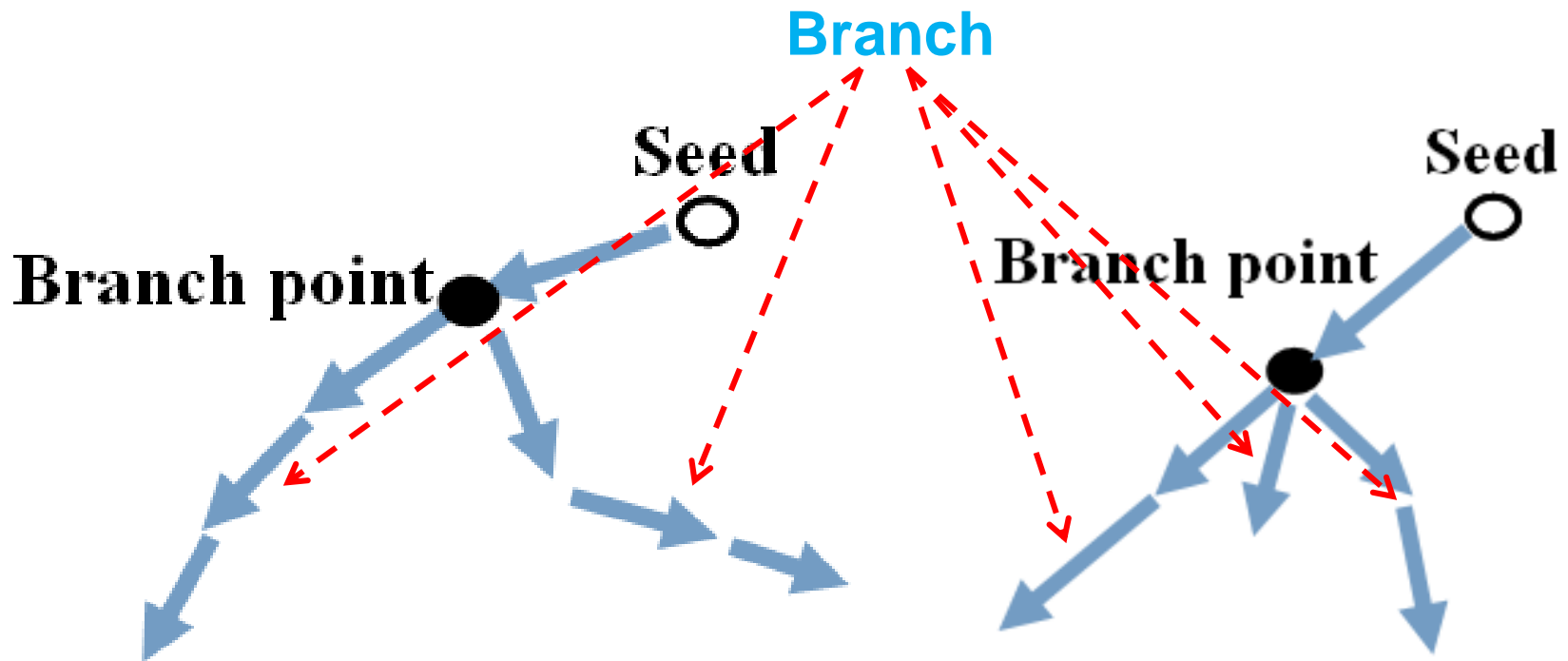
- **Design Gene:** is a vector, string or sequence, of binary values which represents the total behaviour of the design.
- **Design Seed:** is a collection of design genes which characterise a complete product.
- **Tree-like gene** = [ 1, 1, 1, 0, 1 ]

Gene Function	Value	Action
Grow	1	Grow in a direction
Branch	1	Split / fork
Stem	1	Grow vertically only
Leaf	0	Form a surface
Thicken	1	Allowed to get thicker



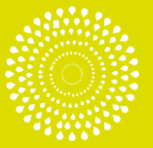


Non-split; grow along any directions  
until a growth criterion is satisfied



Split; grow along any directions until a split condition met, then the shoots split, each with its own new direction and magnitude set.

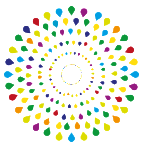




## Blind actions.....

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- Unknown growth occurs in response to stimuli
- Every element persists for the life of the design
- Every element makes its own blind actions, unaware of the overall design

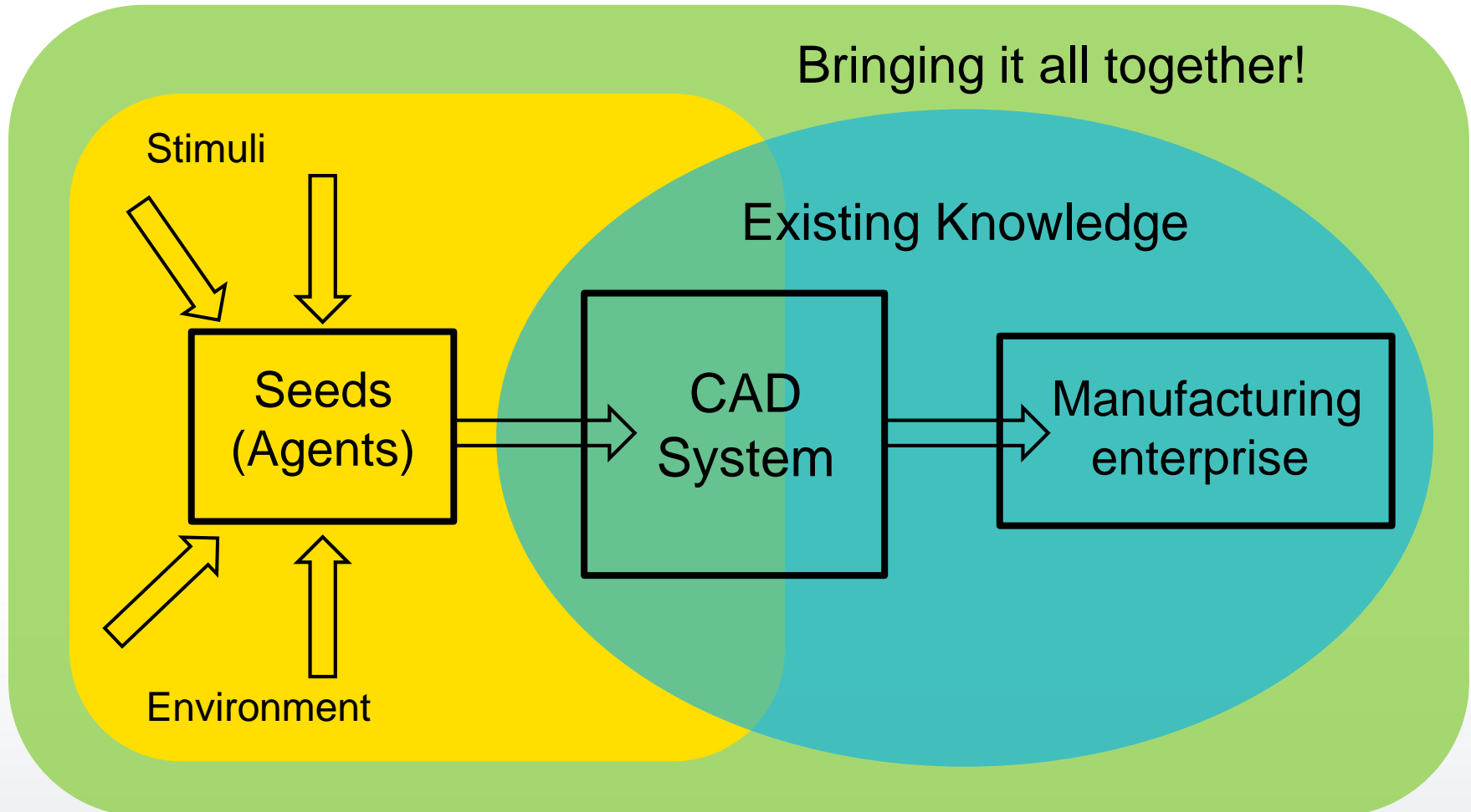


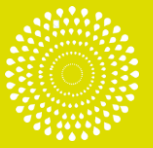
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# INTEGRATED SYSTEM



## PROPOSED SYSTEM SCHEMATIC

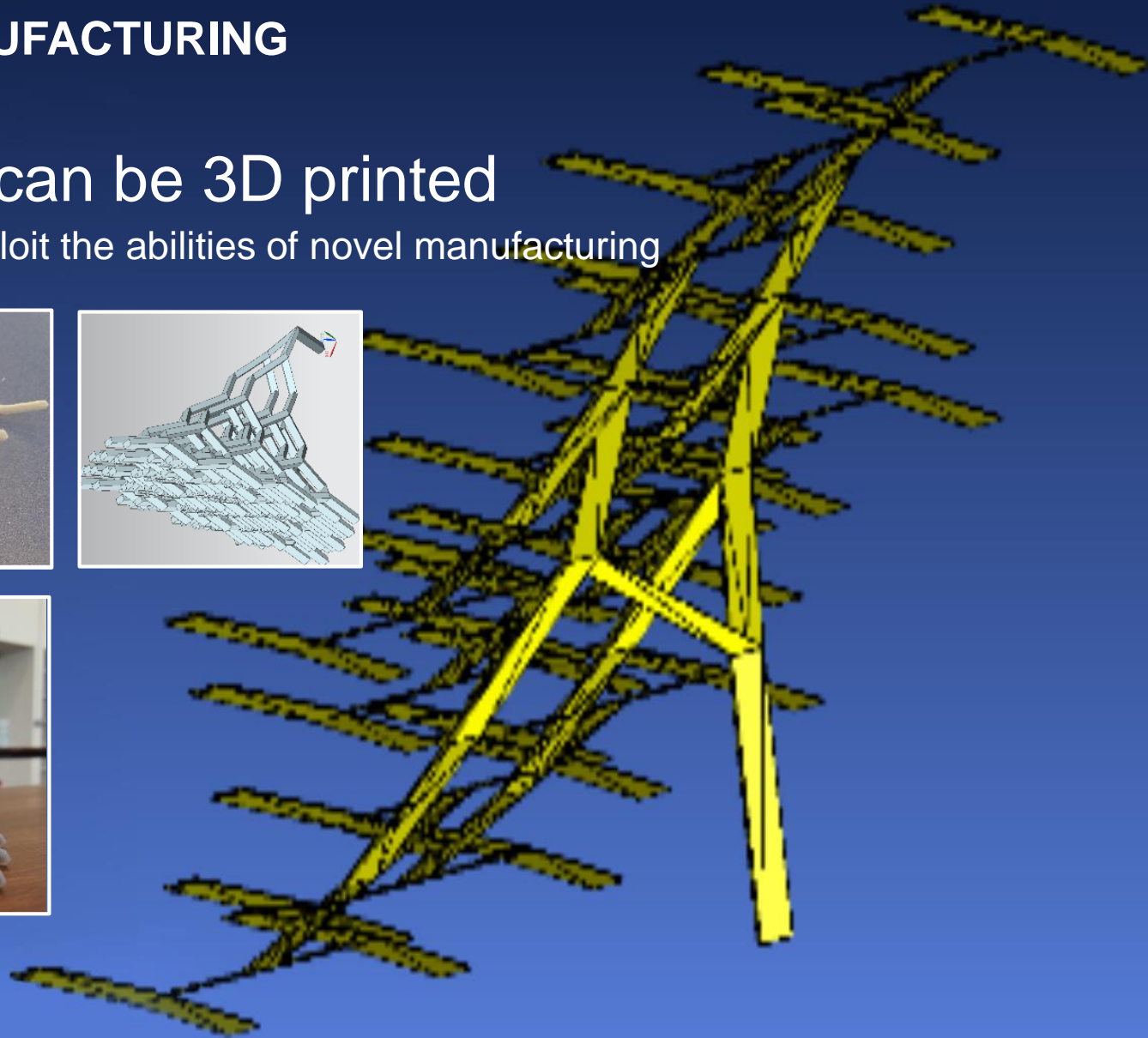
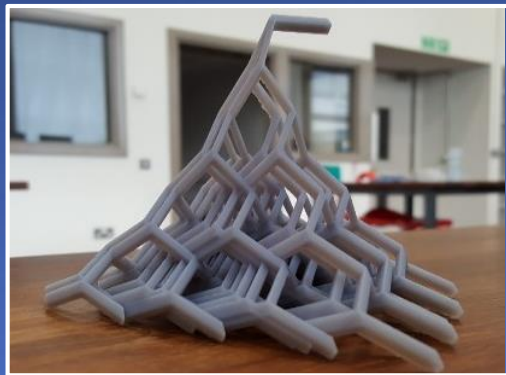
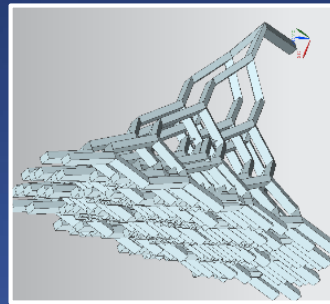




## ADVANCED MANUFACTURING

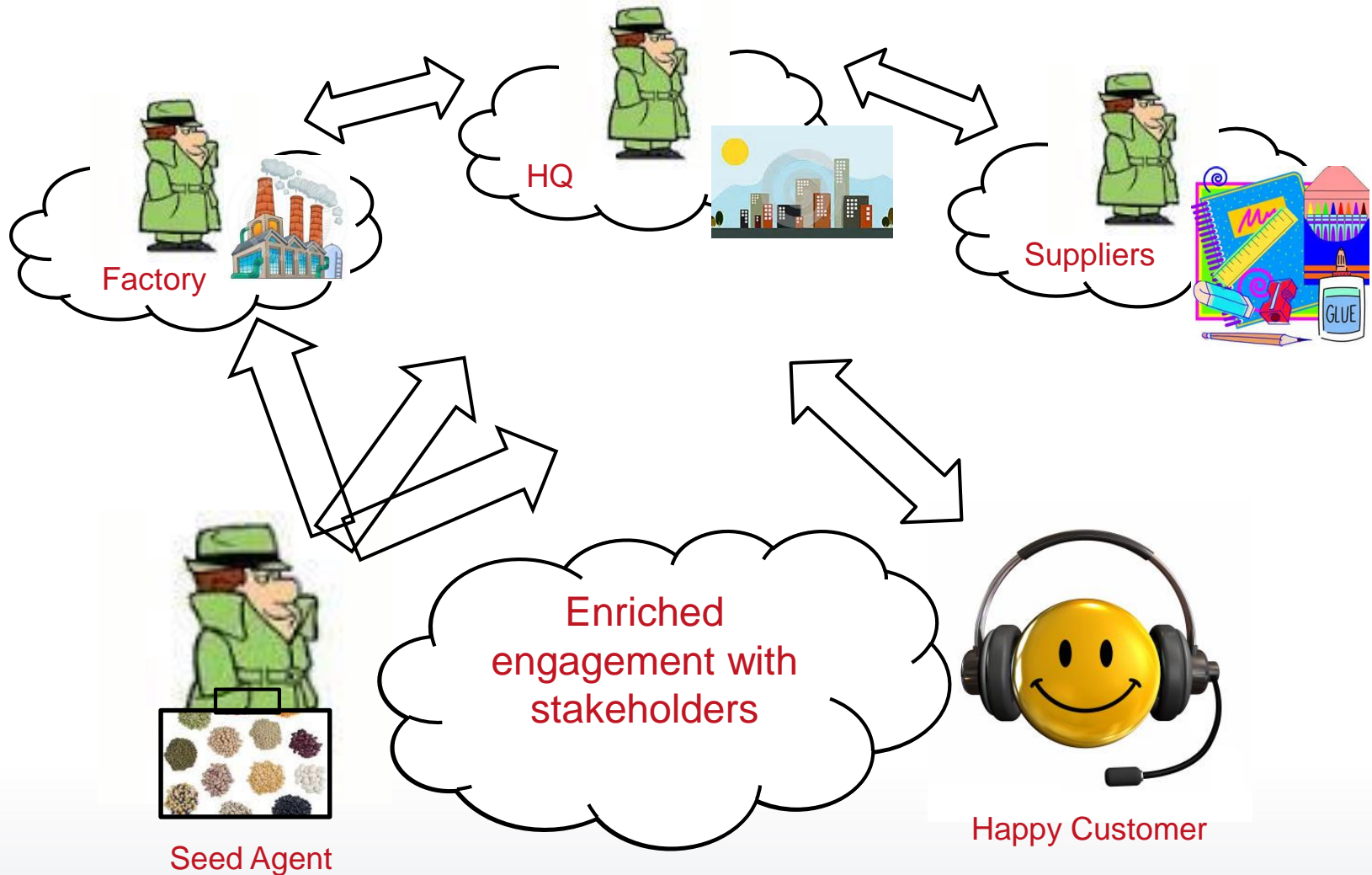
# CAD models can be 3D printed

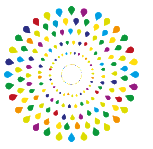
Design process to exploit the abilities of novel manufacturing





## POTENTIAL IMPACT





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# INVESTIGATIONS





$$\min_{S_{seed} (S_x, S_y) \in \vec{V} \in \Omega} T(G_s, G_g)$$

## □ Core algorithm

- Given growth functions for **length** and **angle**

While **growth step**  $G_s < G_g$

    If **condition 1** is satisfied

        Set **design gene type 1** on

        Update length and angle using **growth function 1**

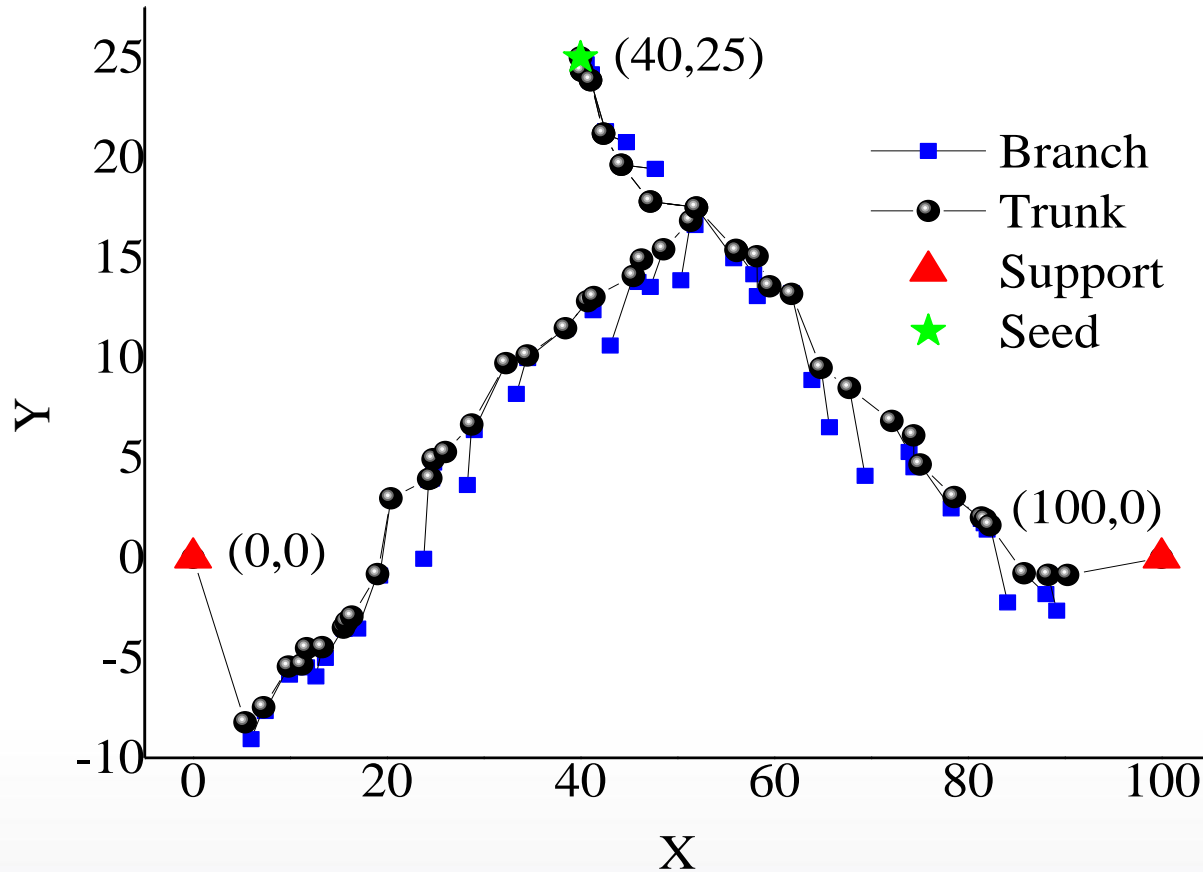
    Else

        Set **design gene type 2** on

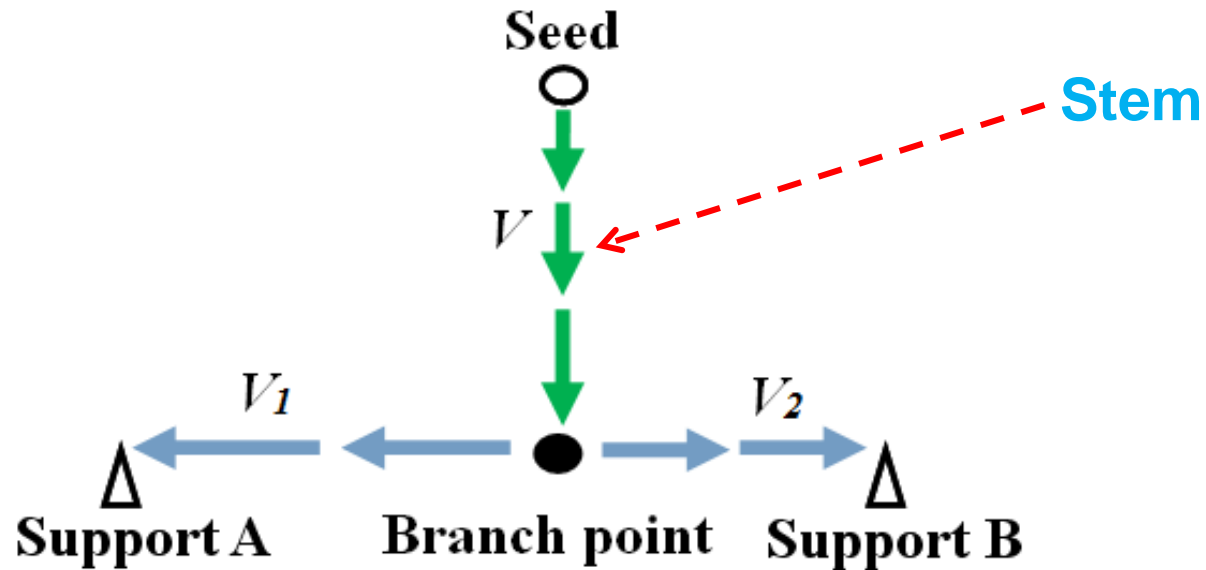
        Update length and angle using **growth function 2**

    End

End



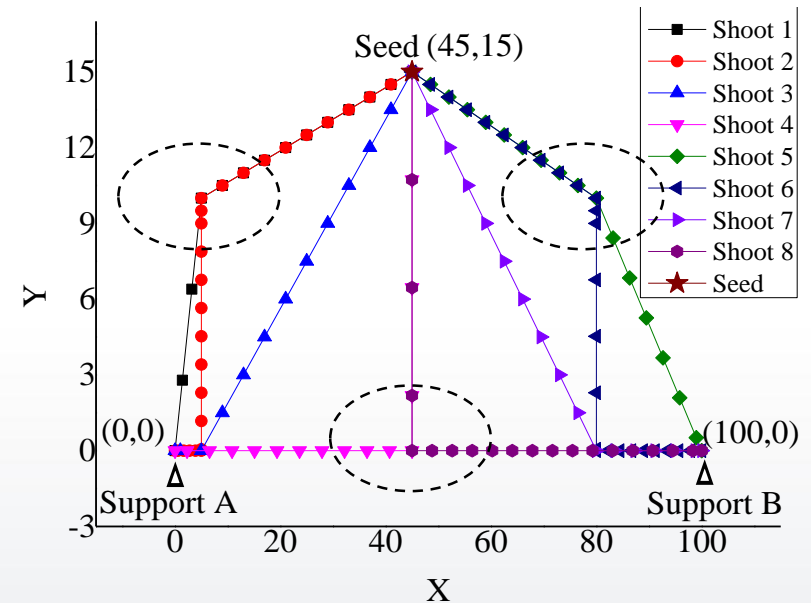
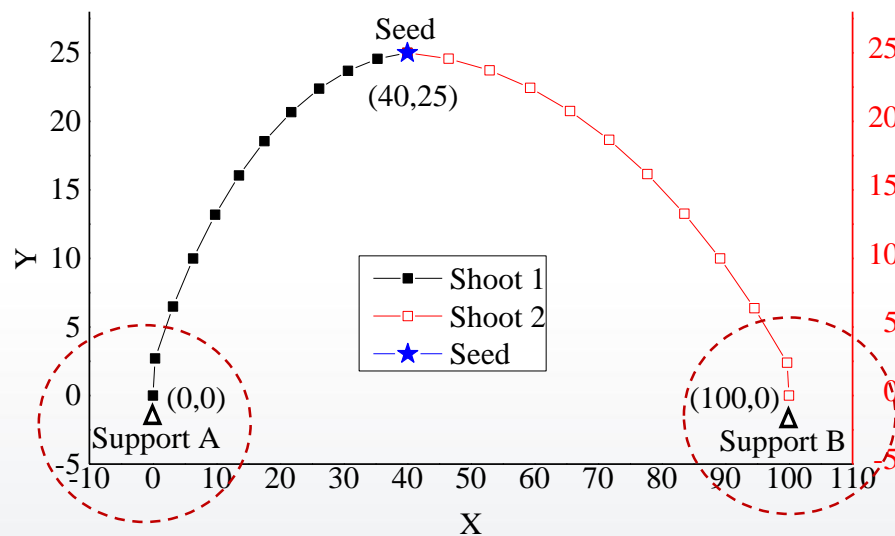
Grow along a random direction and/or length



Grow up or down only



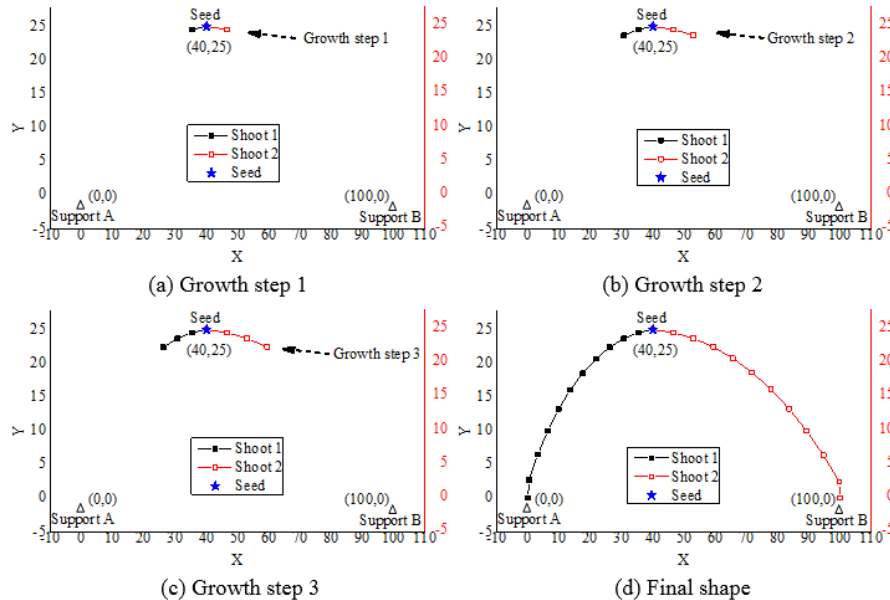
- With simple control rules, it is easy to create familiar structures, like frameworks.



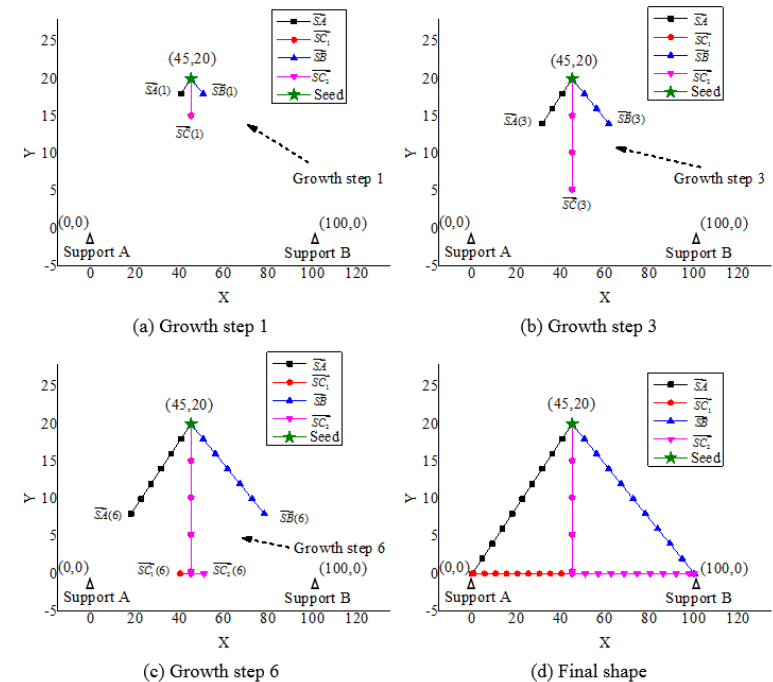


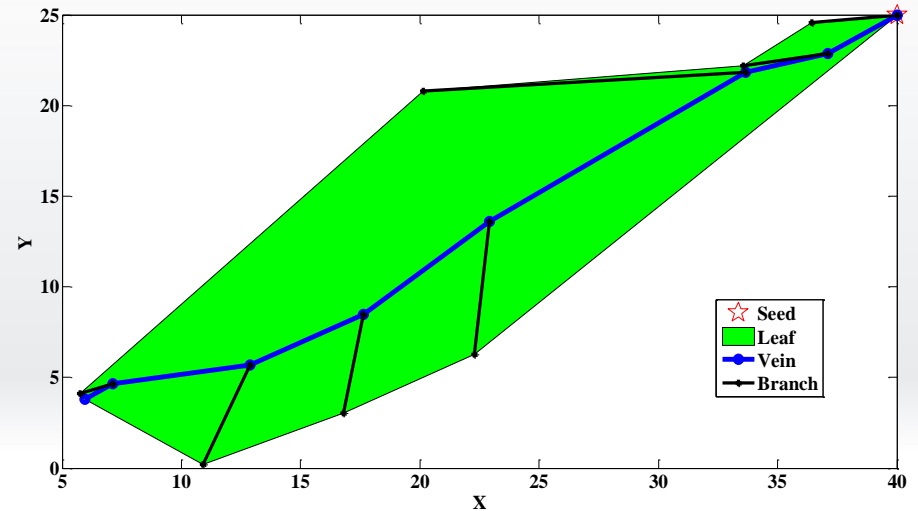
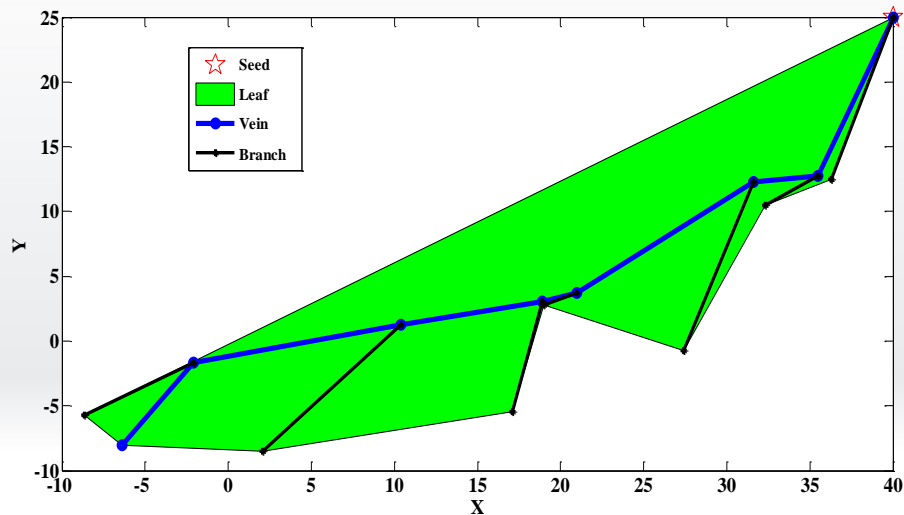
## GENES FOR GROWTH

- Branch at the beginning and then grows towards supports



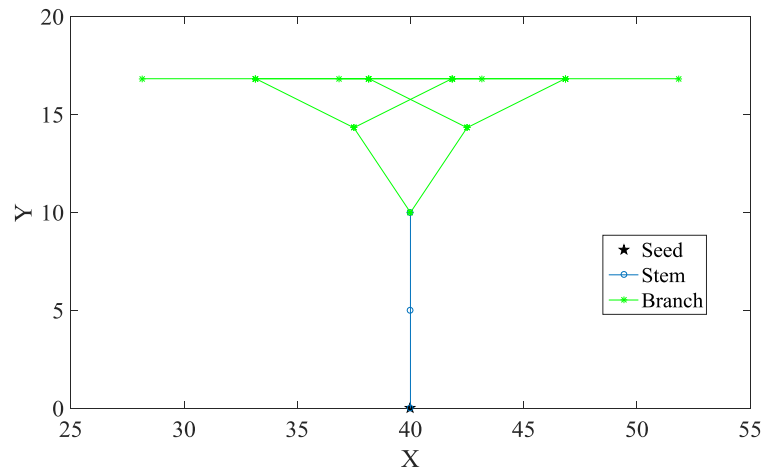
- Branch at the beginning,
  - 1 shoot with stem gene active
  - Stem branches and grows towards support



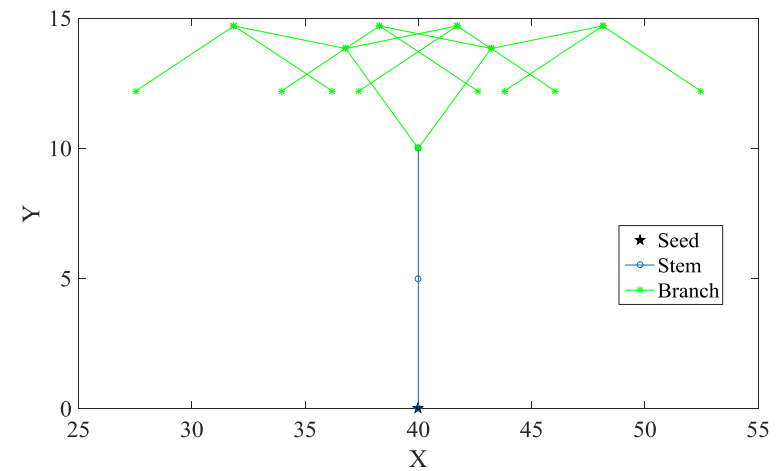


Split; grow along any directions; a surface is formed using all end points of each branch and seed

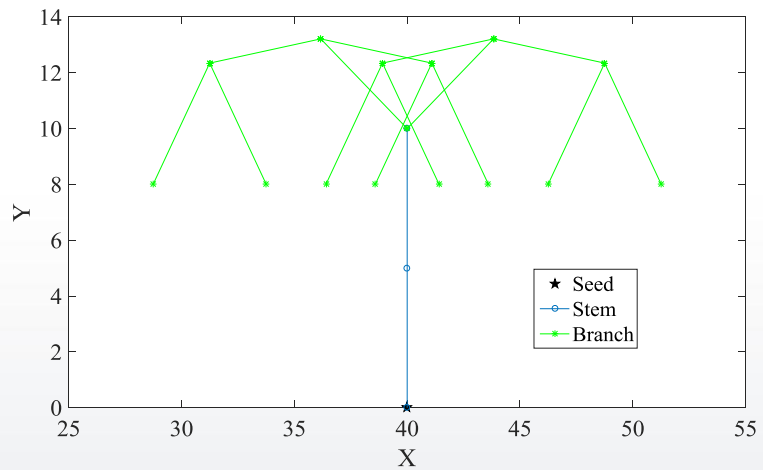




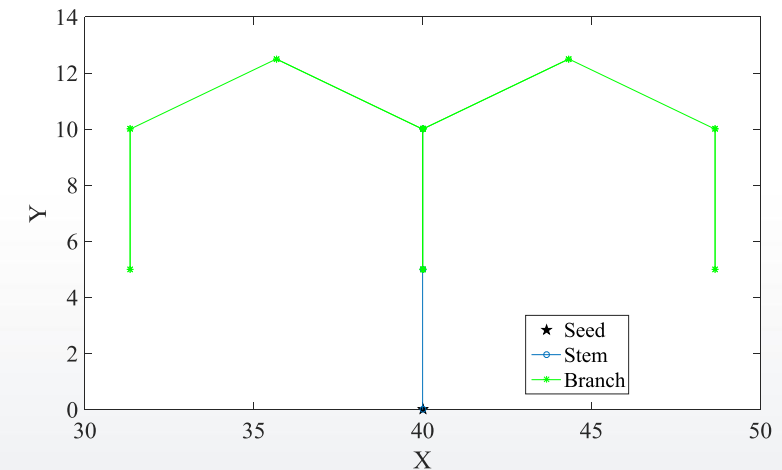
$$angle_{(0)} = 60^\circ$$



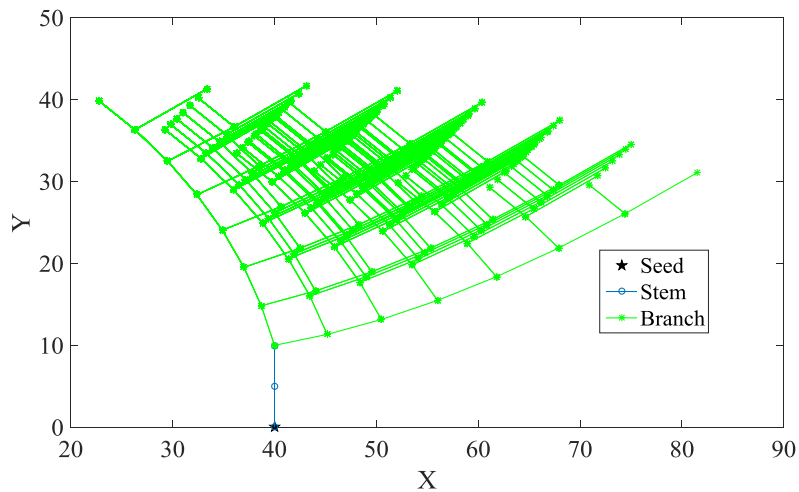
$$angle_{(0)} = 50^\circ$$



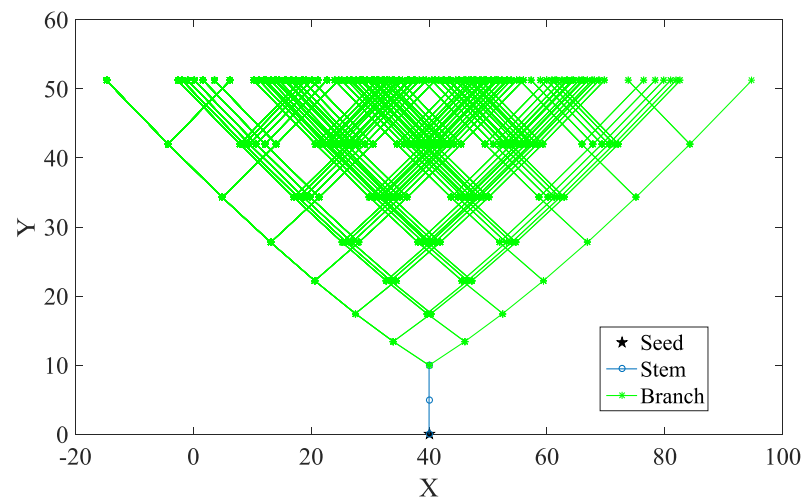
$$angle_{(0)} = 40^\circ$$



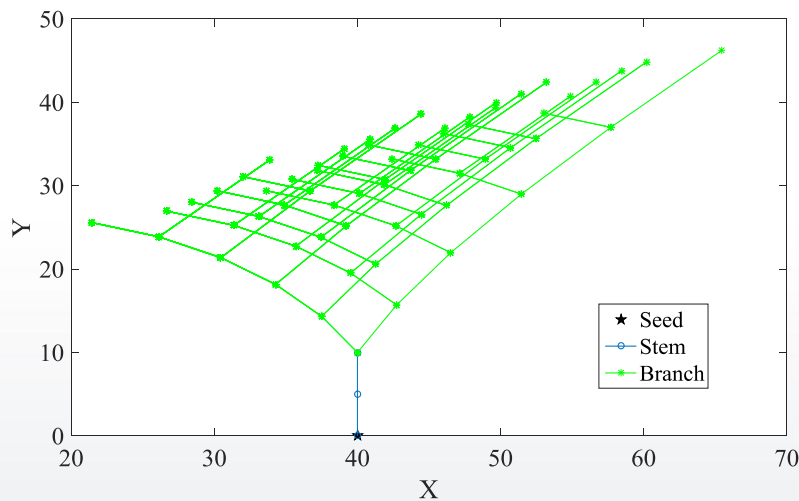
$$angle_{(0)} = 30^\circ$$



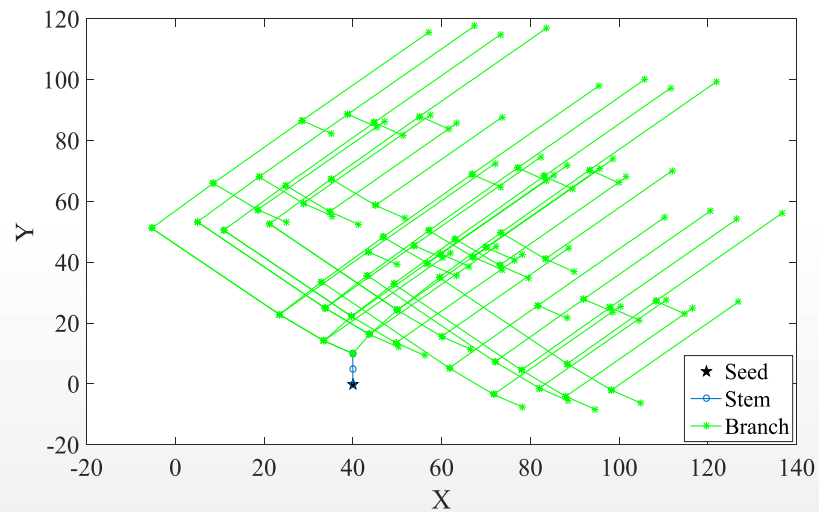
Left: circle; right: hyperbola A



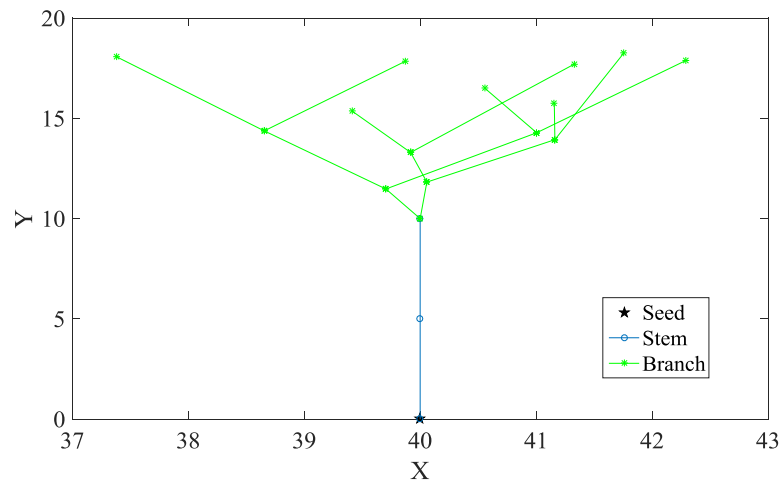
Left and right: hyperbola A



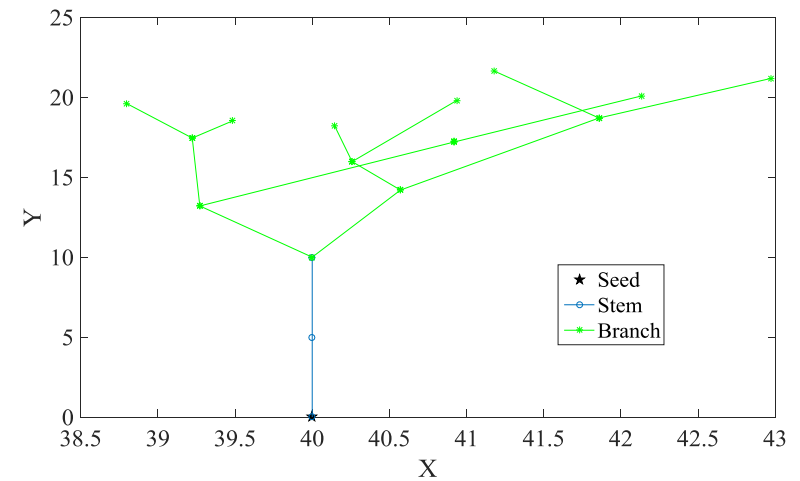
Left: circle; right: hyperbola B



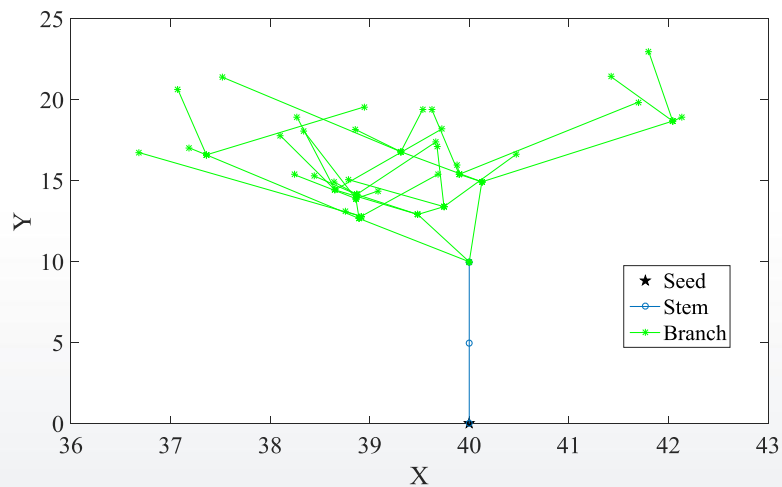
Left: hyperbola A; right: hyperbola B



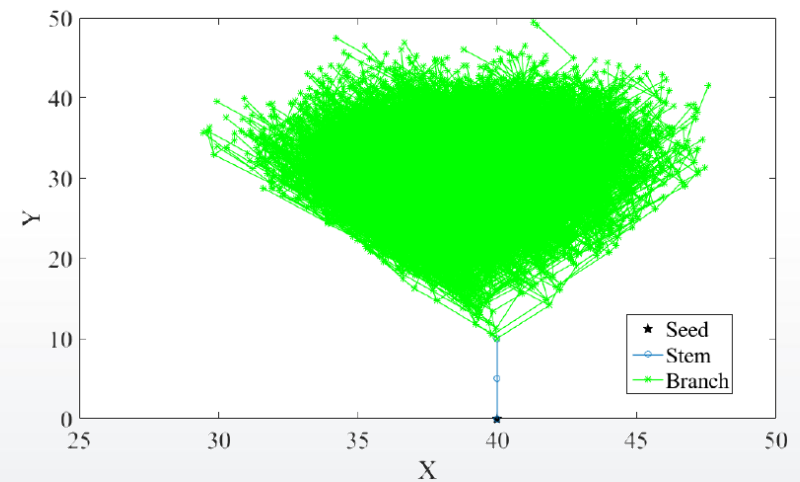
Split step 3, number of branch 2



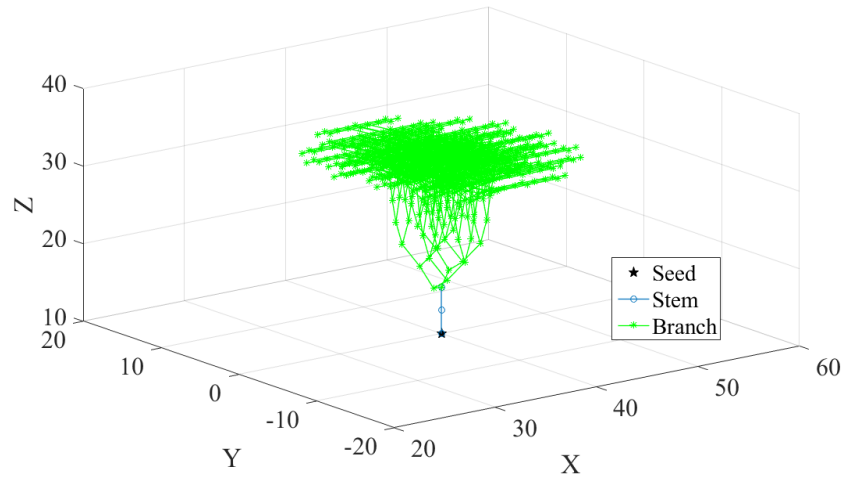
Split step 3, number of branch 2



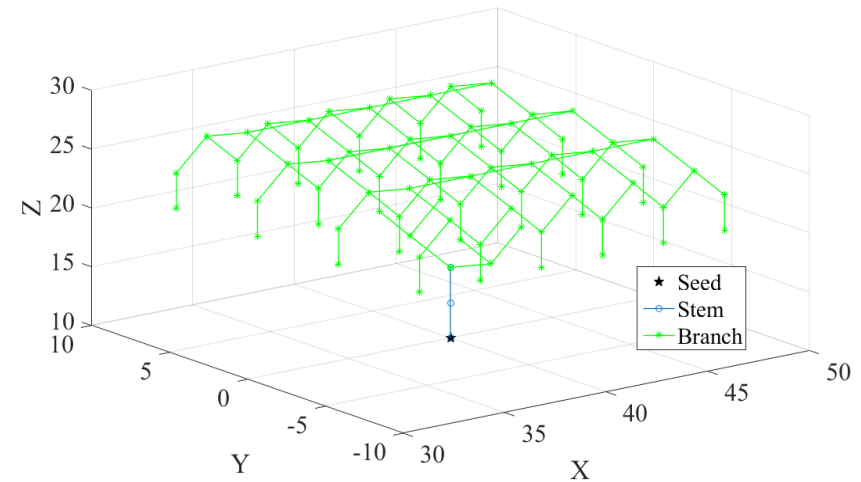
Split step 3, number of branch 3



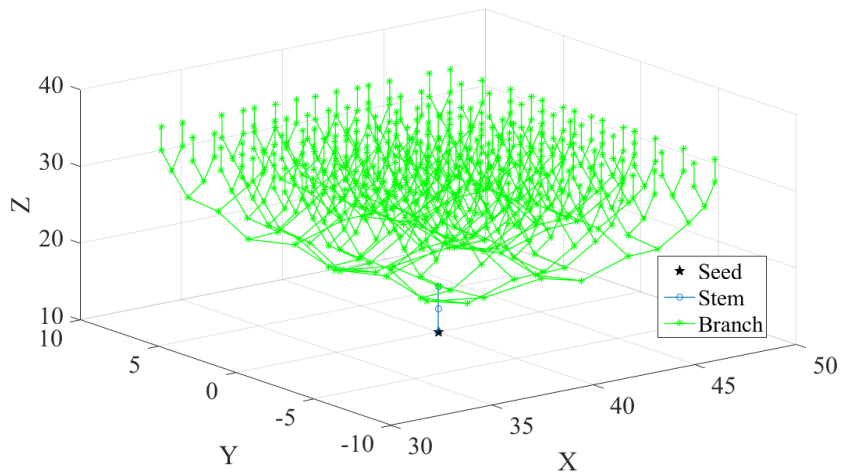
Split step 9, number of branch 3



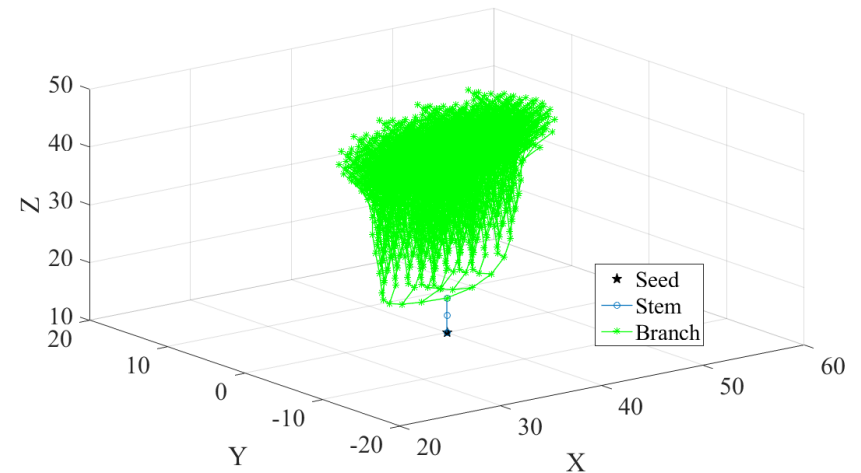
$\alpha = 40^\circ$ ,  $\beta = 20^\circ$ ,  $L=3$ , split step 9



$\alpha = 90^\circ$ ,  $\beta = 30^\circ$ ,  $L=3$ , split step 9



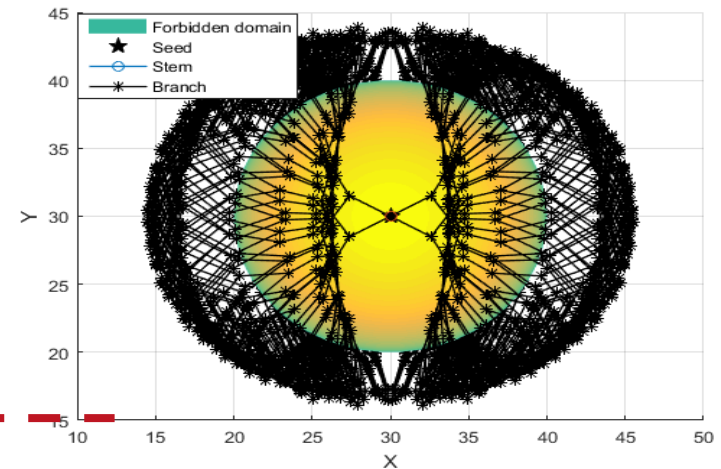
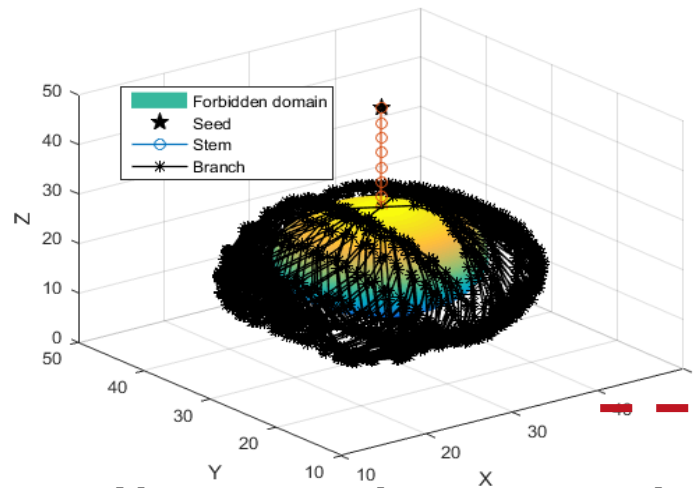
$\alpha = 90^\circ$ ,  $\beta = 10^\circ$ ,  $L=3$ , split step 9



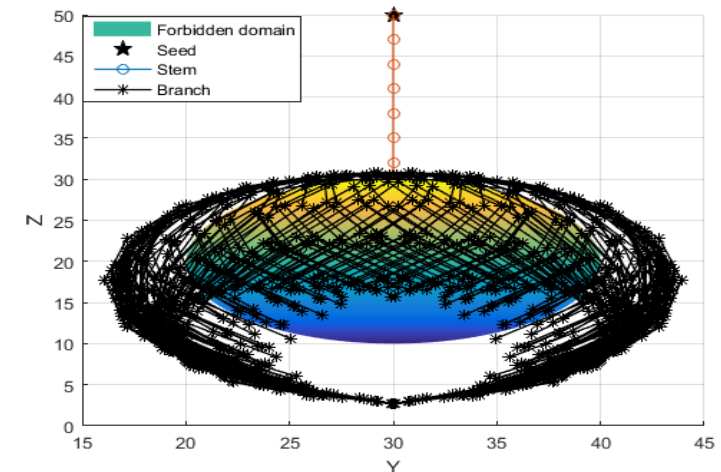
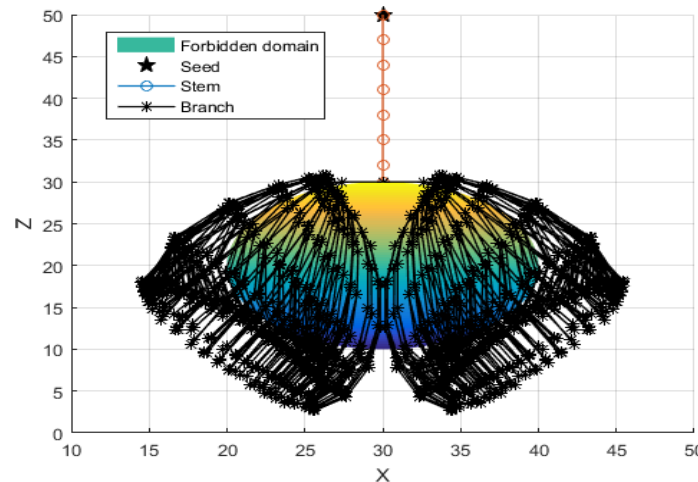
$\alpha = 10^\circ$ ,  $\beta = 10^\circ$ ,  $L=3$ , split step 15



**3D CASE:**  $\alpha = 15^\circ$   $\text{bate} = 30^\circ$ , split step = 9

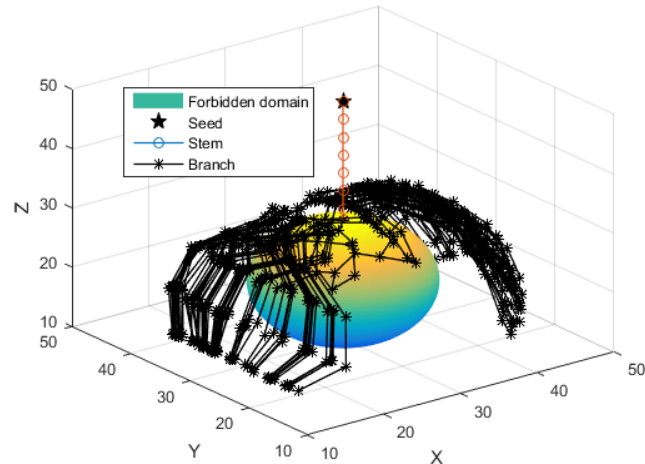


**No contact between endpoints and the surface of a forbidden domain **except** the initial touched point**

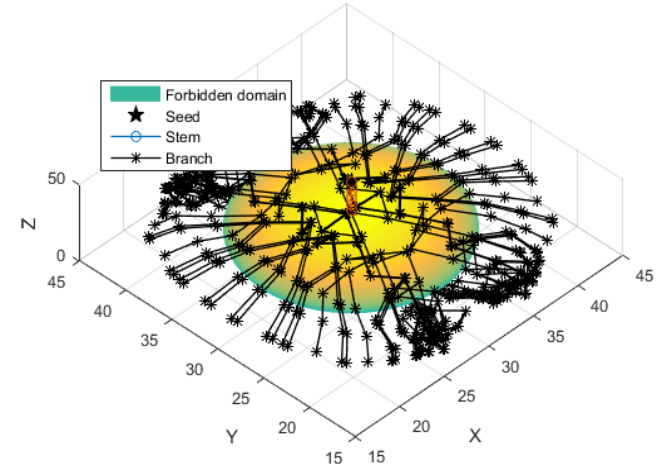




# PARAMETER STUDY: angle and split step

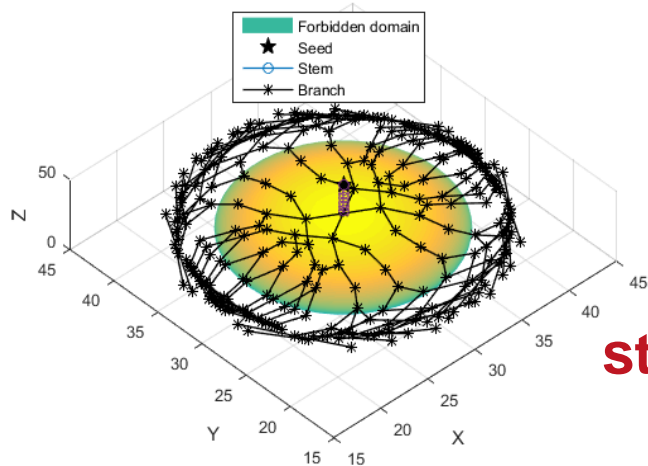


$\alpha = 45^\circ$ ,  $\beta = 45^\circ$ , split step = 11z

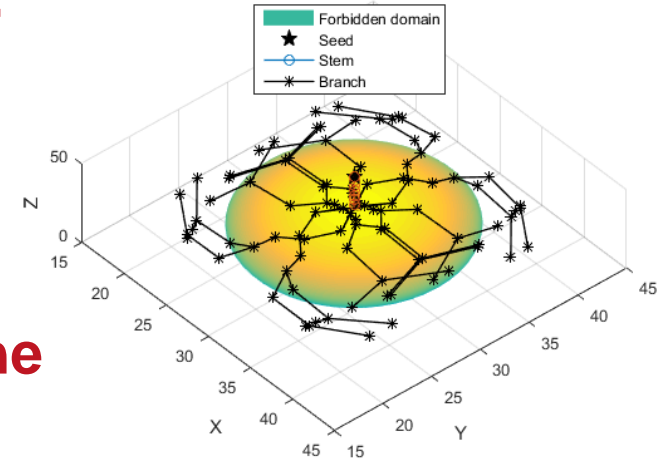


$\alpha = 10^\circ$ ,  $\beta = 120^\circ$ , split step = 9

Case 1 | Case 2  
Case 3 | Case 4



$\alpha = 30^\circ$ ,  $\beta = 30^\circ$ , split step = 6

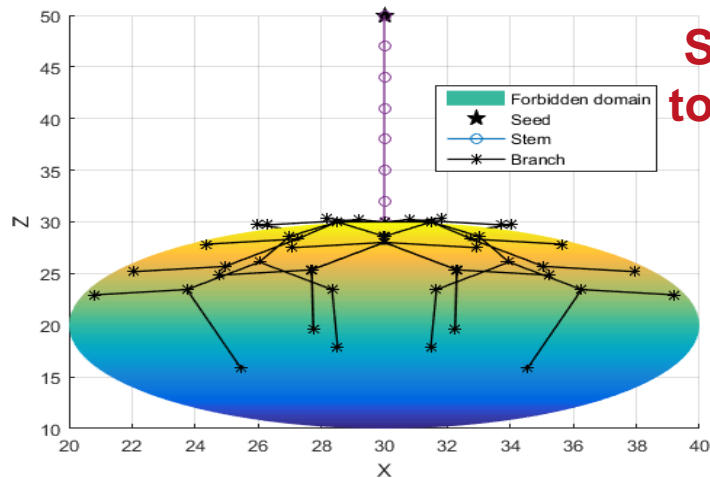
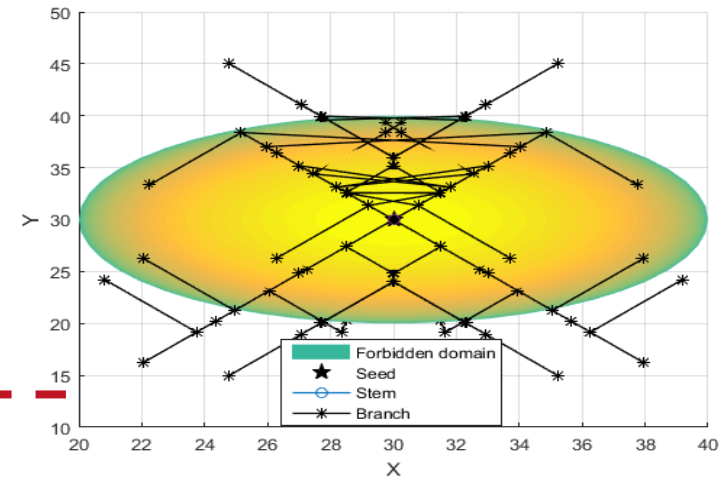
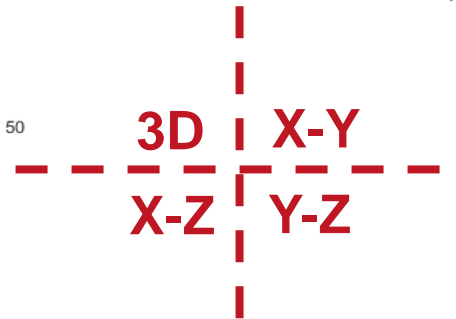
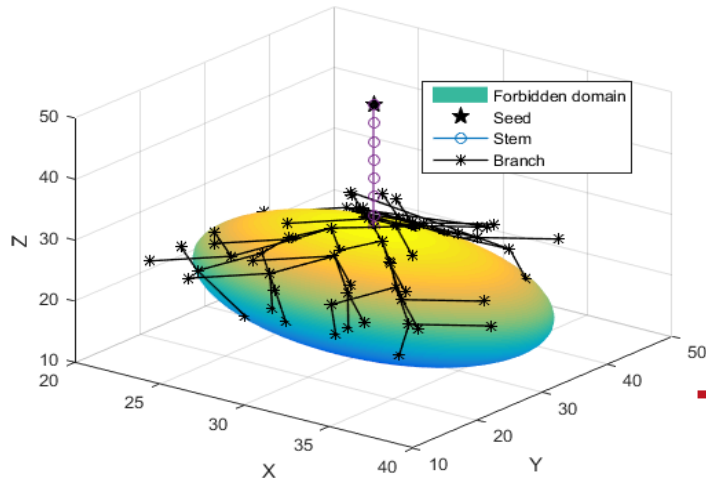


$\alpha = 30^\circ$ ,  $\beta = 60^\circ$ , split step = 6

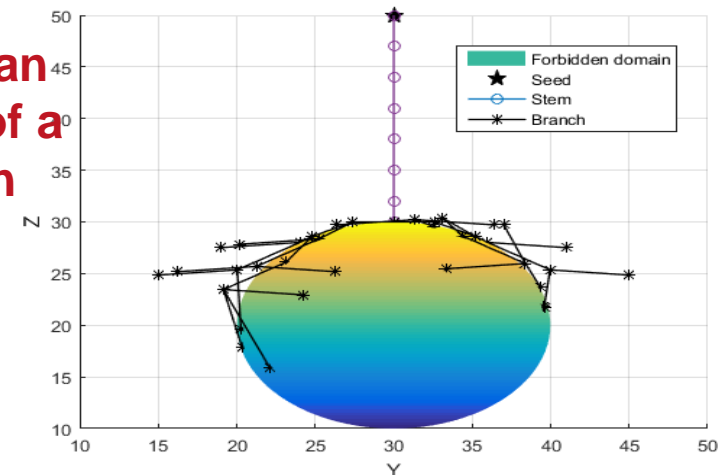
Angle and split  
step can regulate the  
growth of design



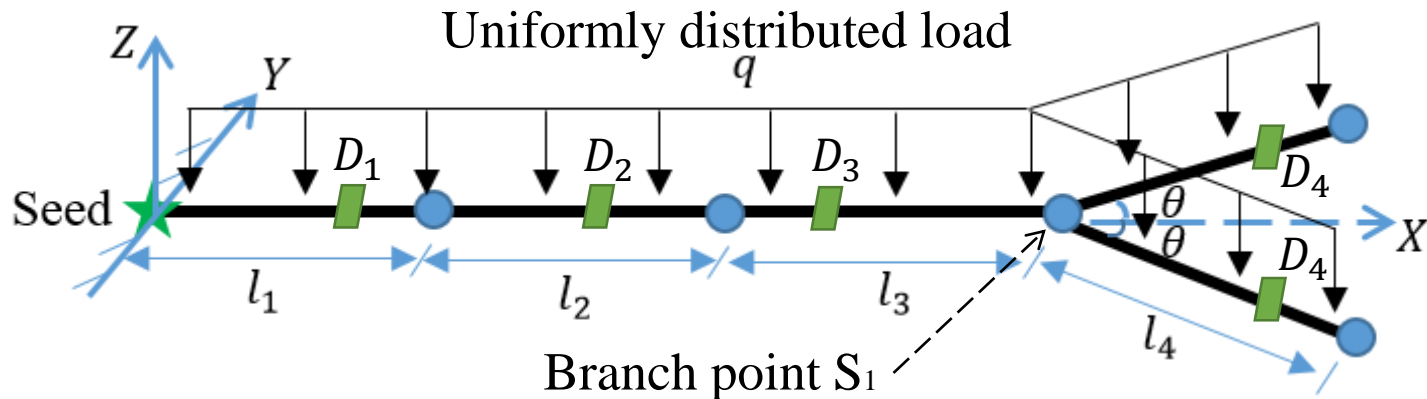
**3D CASE:**  $\alpha = 25^\circ$   $\beta = 60^\circ$ , split step = 7



**Some endpoints can touch the surface of a forbidden domain**







- **Outer loop: update total energy using strain energy**

$$U_{T(i)} = U_{T(i-1)} - U_{\text{strain}(i)} = U_{T(i-1)} - \int_0^L \frac{M(x)^2}{2EI} dx > 0$$

- **Inner loop: update maximum stresses of each section**

$$\sigma_{\text{max}(i,j)} = \frac{M_{\text{max}(i,j)}}{I_{i,j}} y = (ql_{i,j}^2/2)/(\pi D_{i,j}^3/32) > \sigma_{\text{allow}}$$





## Update length and diameter

$$l_{i,j} = \sqrt{\frac{(\pi \sigma_{allow} D_{i,j-1})^3}{16q}} - l_{i,j-1}$$

$$D_{i,j} = \sqrt[3]{\frac{16ql_{i,j}^2}{\pi \sigma_{allow}}}$$

$i$ : growth step;  $j$ : index of emerged beams

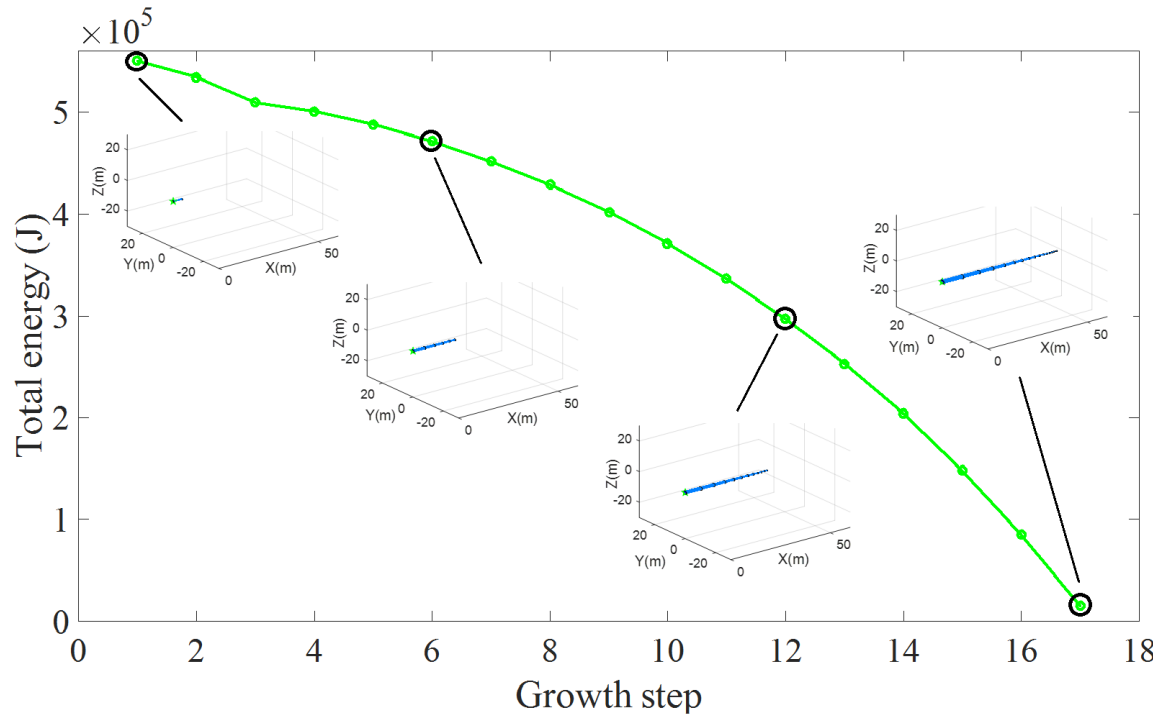
$$l_{i,j} = l_{i,j} \cdot f_l \quad \text{if } j = 1$$

**Growth factor**

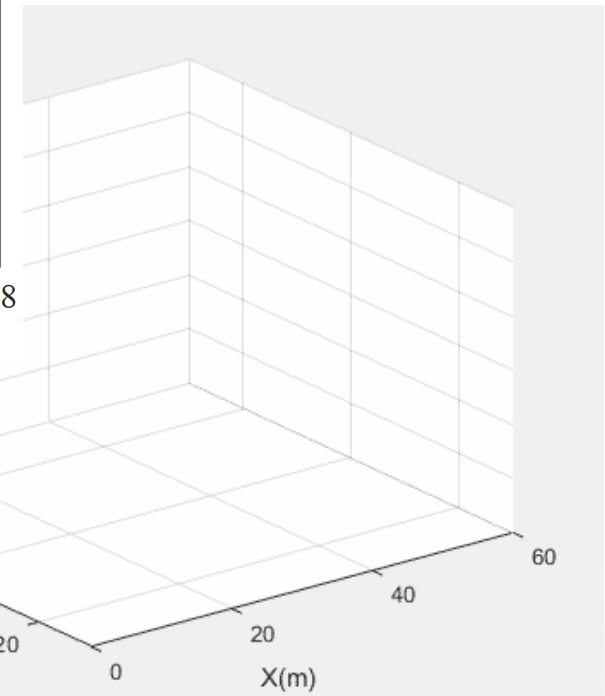
$$D_{i,j} = D_{i,j} \cdot f_D$$



# Energy history of the growth process



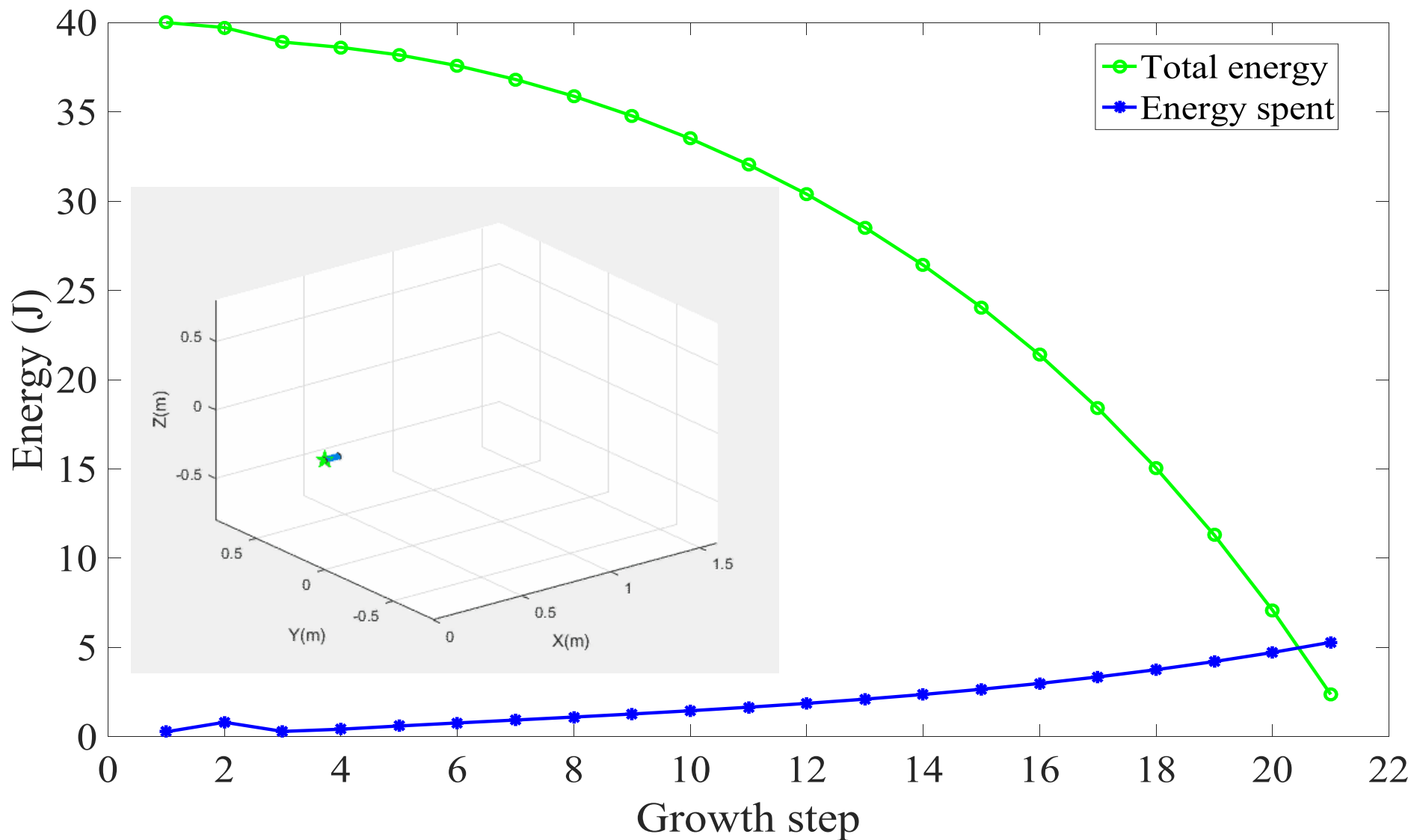
▼ Animation of the growth process



▲ The growth stops when the total energy consumed nearly to 0

# Growth with random branches

**Environment:** Uniformly distributed load  $q=3 \times 10^5 \text{ N/m}$



# Growth with complementary energy

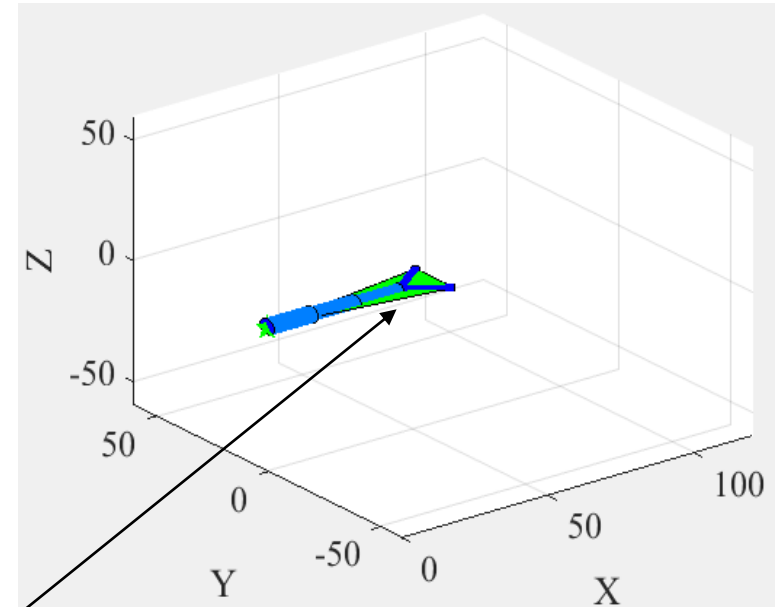
## □ Basic idea

- Calculate complementary energy using leaf area and a coefficient:

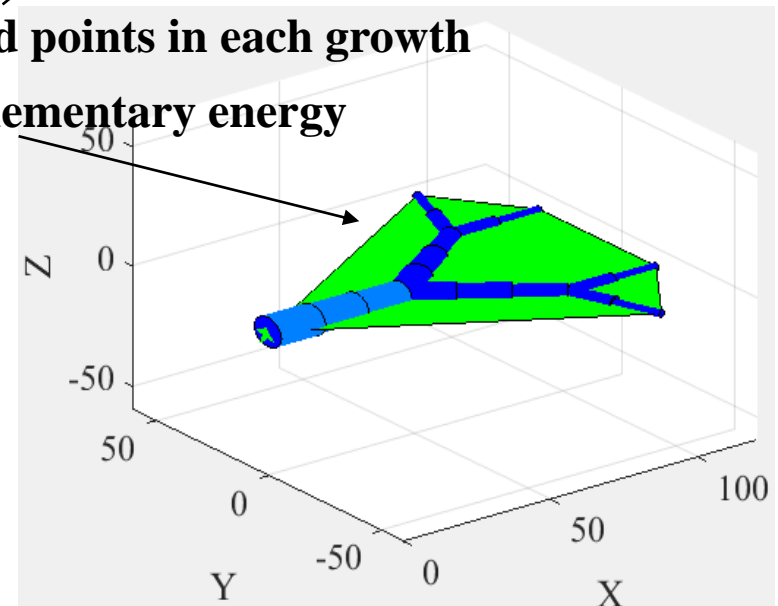
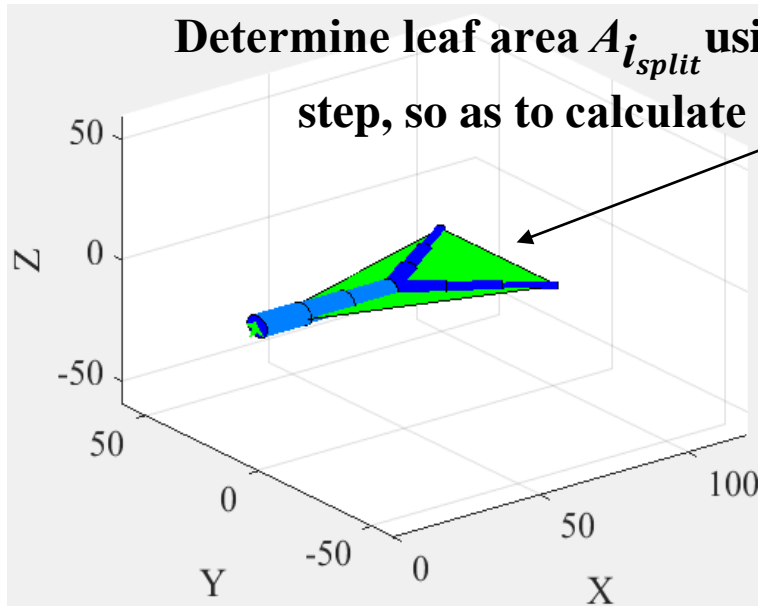
$$U_{c(i)} = f_c \cdot A_{i_{split}}$$

- Update total energy using strain energy and complementary energy :

$$U_{T(i)} = U_{T(i-1)} - U_{\text{strain}(i)} + U_{c(i)}$$

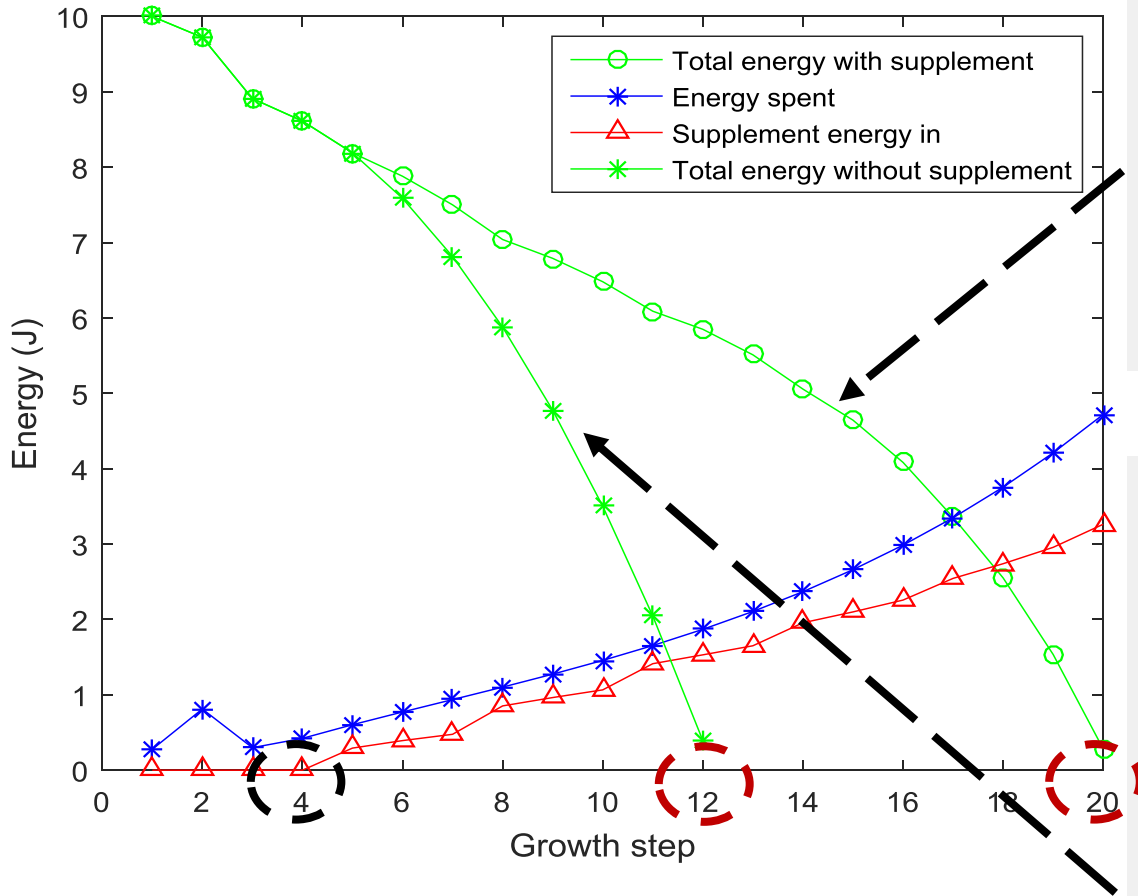


Determine leaf area  $A_{i_{split}}$  using end points in each growth step, so as to calculate complementary energy

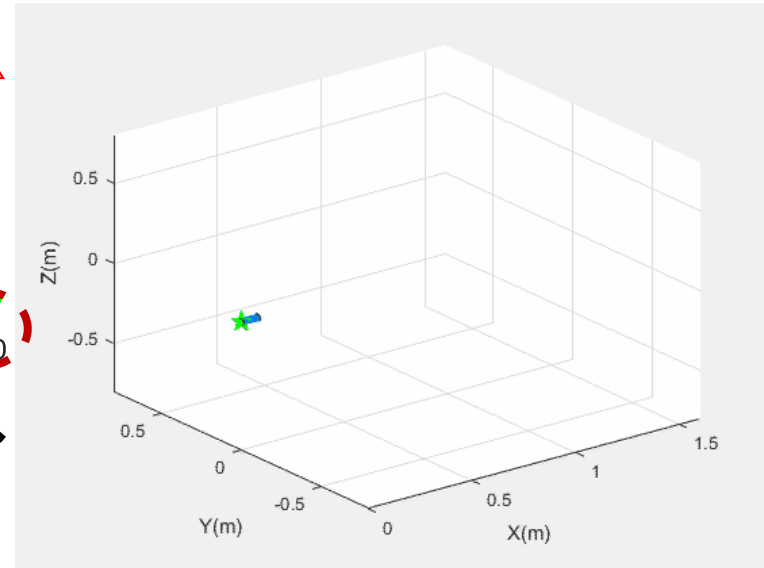
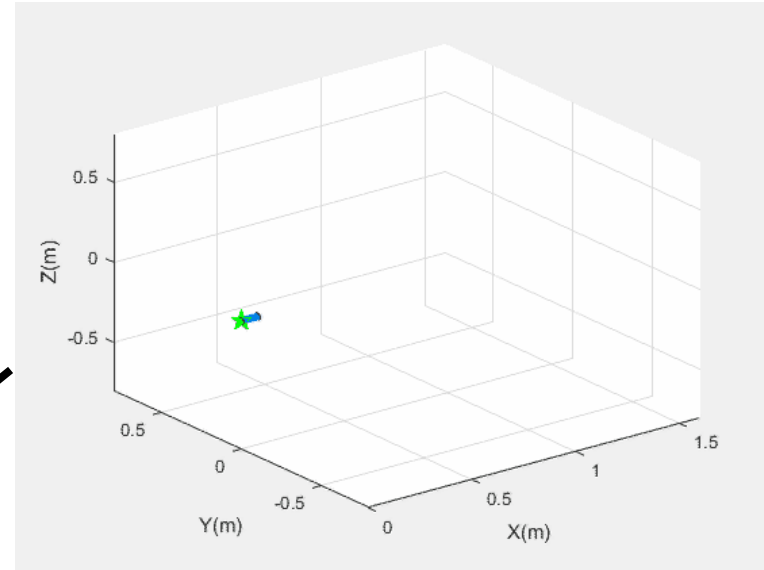


# Comparison of growth with and without supplement energy

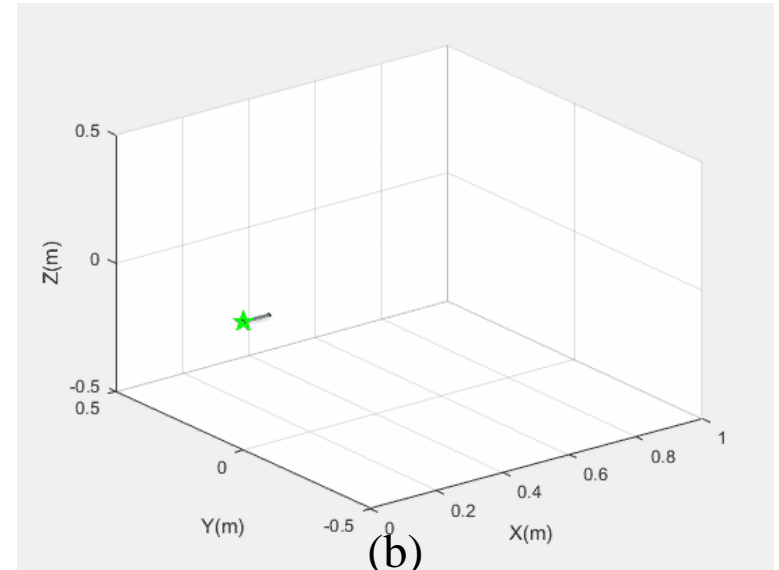
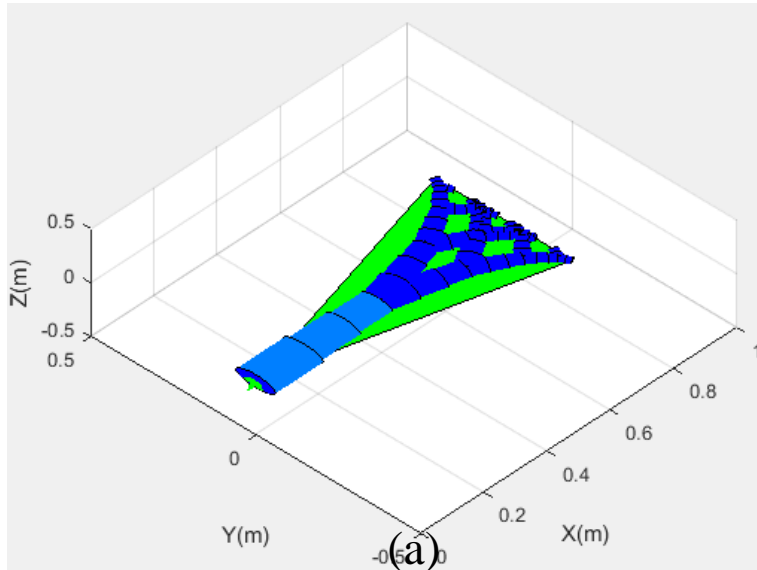
**More growth steps can be guaranteed by supplement energy, so that complex structures should be formed.**



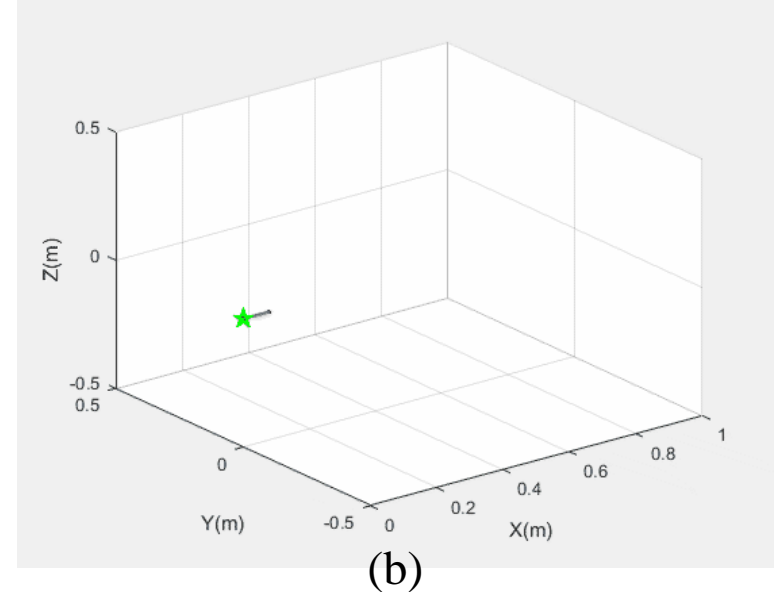
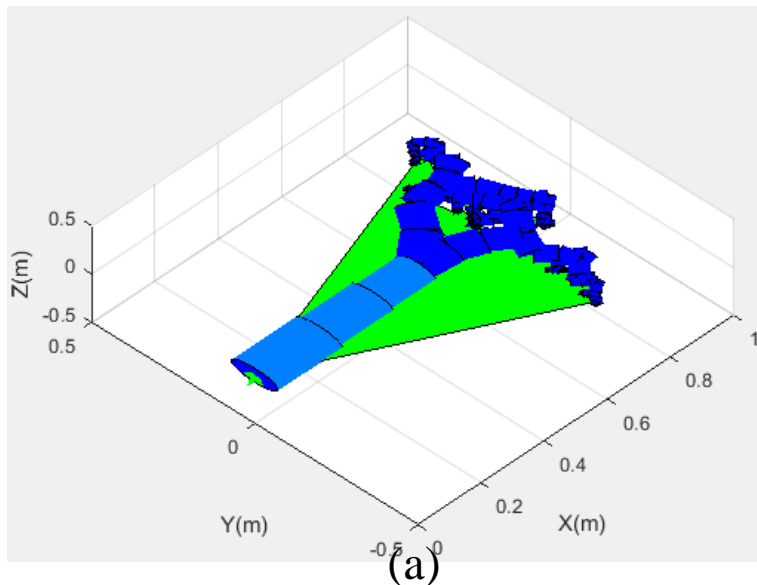
**Supplement energy added by leaf surface**  
using  $U_{c(i)} = f_c \cdot A i_{split}$ .



# Growth with branches and complementary energy



▲ initial  $\theta_0 = 15^\circ$ , **determinate** branches, (a):final shape; (b) animation



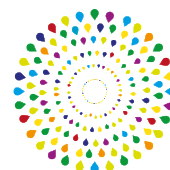
▲ initial  $\theta_0 = 60^\circ$ , **random** branches, (a):final shape; (b) animation



## GEOMETRY CHALLENGES

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- How can a useful parameterization be extracted?
- Dealing with multi-disciplinary mixed dimensional simulations?
- System architecture always changing – requires dynamic CAD representations?
- System elements always changing – requirement for persistence.
- Search space increases exponentially – scalable solutions?



biohaviour

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# THANK YOU!

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