

REAL WORLD INDUSTRIAL ROBOTICS SIMULATION FOR STUDENTS

TOUCH

MotoSim

COMPLETE VIRTUAL INDUSTRIAL ROBOTIC SOLUTION FOR STUDENTS

KEY BENEFITS

Provides "real world" virtual robotics experience at a fraction of the cost of an industrial robot

Provides hands-on, STEM-aligned environment for robotic modeling and programming

Teaches industry-recognized career ready robotics skills

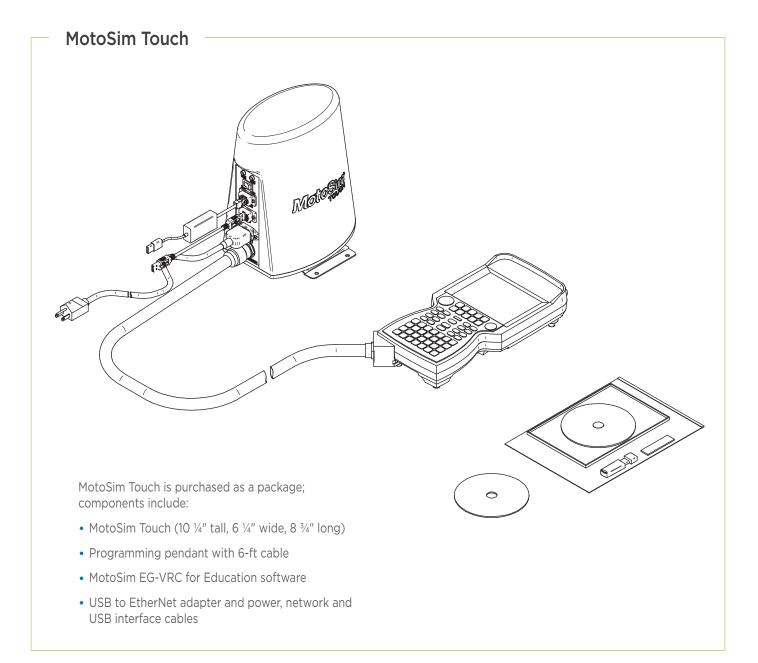
SYSTEM REQUIREMENTS -

Recommended	Minimum
Windows [®] 7 (64 bit) or Windows [®] 10 (64 bit)	Windows® 7 (32 bit)
Intel Core i5 CPU	Intel Core 2 Duo CPU
4-8 GB RAM	2 GB RAM
3D Pro graphics card	3D graphics card
4 GB of free hard drive space	



- PC-based offline programming environment and robotics simulation tool.
- Designed specifically for K-16 schools, training organizations and educational research institutions.
- Simulates a fully functional production environment.
- Setup in the classroom or robotics lab is quick and easy, with only four cables to plug in.
- Provides the ability for students to toggle between a virtual pendant and a hardware pendant.
- In either mode, students utilize MotoSim EG-VRC* for Education, a comprehensive offline programming and simulation software package.
- Virtual pendant and hardware pendant both utilize easy-to-use INFORM III programming language.
- Robot programs can be moved from the simulation environment to the classroom robot.

- Learn how to program and model industrial robots in a safe, virtual PC environment:
 - Enter and modify data to create a robot job
 - Perform collision detection, reach analysis and cycle time calculations
 - Perform testing and diagnostics
- Download robot job to robot controller
- Learn how to program robots using a hardware pendant. Practicing with a pendant develops "muscle memory", allowing programming tasks to become second nature.
- Become proficient with a wide variety of robot functions, including:
 - Robot path
 - Speed
 - TCP (tool center point)
 - User frames
 - I/O monitors
 - Macro command
 - Relative job
 - Enhanced multiple robot control
 - Independent/coordinated motion
 - External axis control and coordination
 - User definable view





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