# **YASKAWA**



Comprehensive Palletizing Software Suite

### **Key Benefits**

Fast development and deployment of complex palletizing workcells

Offline (PC-based) pallet pattern generation and cell definition

Online (controller-based) execution and optimization of the palletizing operations

## Compatibility

YRC1000

DX200

MLX300

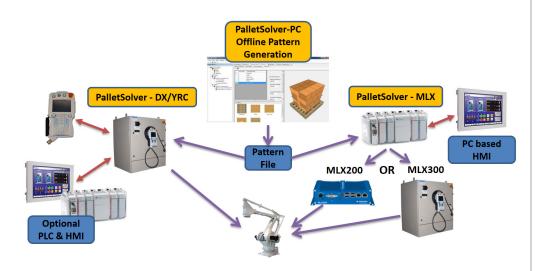
MLX200



- Easy-to-use configuration, setup and customization routines enable fast development and integration of robotic palletizing systems.
- Two components PalletSolver-PC and PalletSolver-Online – separate the definition and configuration on the PC from the execution on the controller.
- Scalable architecture easily handles single and complex multi-line palletizing, as well as single and multiple workcells.
- Interference zones can be designed to limit arm movement, avoiding collisions with surrounding equipment.
- Offline pattern development and sequencing is separate from production which facilitates quick changeover of patterns or products without system downtime.

- Multiple gripper types (fork, vacuum, clamp, bag) can be accommodated.
- Dynamic gripper zones enable flexibility for handling various product sizes.
- Adaptable for various end-of-line processing requirements, such as a single infeed to multiple build stations or single infeed with multiple products to multiple build stations.
- Support for smart conveyors.
- · Label placement flexibility.
- Accommodates virtually unlimited SKUs (Stock Keeping Units).
- Pattern files, in XML format, are transferred to the controller via network or USB thumb drive.
- Directly import pallet patterns from third party tools (CAPE/TOPS).

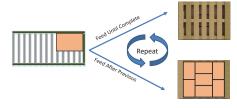
# **PalletSolver**



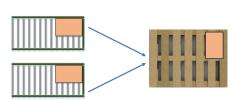
# Typical Architecture



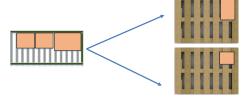
Single Infeed to Single Build (Normal)



Single Infeed to Alternating Builds



Multiple Infeeds to Single Build (Single Product)



Single Infeed to Multiple Builds (Mixed Product)

### **End of Line Options**

#### **KEY PALLETSOLVER FEATURES**

System configuration options:

- 8 Infeeds
- 8 Build stations
- 2 Pallet dispensing stations
- 2 Slip sheet dispensing stations

Gripper options (vacuum, bag, fork, clamp)

Gripper configuration options:

- 8 7ones
- 32 Grip areas
- 32 Sensors

Smart conveyor support

Interference zone definition

TOPS/CAPE importing

Flexible build station configurations

Optimized path planning

Sequencing options (round robin, priority, ratio balancing, override)

Export to XML

Automatic reject station

### MINIMUM REQUIREMENTS

#### Offline

Windows® 7

Microsoft® .NET Framework 3.5

400 MHz processor, recommended 1 GHz

128 MB RAM, recommended 1 GB

30 MB hard disk space

1280 x 1024 screen resolution

### YRC1000 and DX200

Controller software with MotoPlus™ support

64 MB programming pendant

256 MB industrial grade compact flash card or USB flash drive

#### MLX-Series

1769 CompactLogix™ controller with built-in ethernet

- OR -

1756 ControlLogix®/GuardLogix® safety controller, 1756-ENBT ethernet module

3 MB memory on PLC

Studio 5000 Logix Designer® V 24 minimum

FactoryTalk® View ME Station version 7; 75 display activation

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