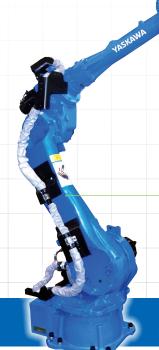


HIGH-SPEED, LOW-PROFILE DESIGN



MH50 II MH50 II-35

COATING | DISPENSING | MACHINE TENDING MATERIAL CUTTING | MATERIAL HANDLING | PRESS TENDING

KEY BENEFITS

Variety of payloads and reaches allow MH-series robot models to be used for a variety of projects.

High speeds and mounting flexibility allows use in a variety of applications.

High wrist ratings provide higher handling capacity.

SPECIFICATIONS

MH50 II:

- 50 kg payload
- 2,061 mm horizontal reach
- 3,578 mm vertical reach

MH50 II-35:

- 35 kg payload
- 2,538 mm horizontal reach
- 4,448 mm vertical reach
- ±0.07 mm repeatability

- Powerful, high-speed robots with long/extended reaches offer superior performance in coating, dispensing, material cutting and handling applications.
- Wide work envelopes with small interference zones, allow robots to be placed close to workpieces/equipment which reduces required floorspace.
- Highly reliable, six-axis robots feature high-rigidity speed reducers and high-speed motion which reduce cycle times.
- High payload moment and inertia ratings allow these robots to handle larger and heavier payloads.
- Cables and air lines are routed through robot base to upper arm to increase cable life, enhance safety and reduce teaching time.

- Cable installation tube in robot base facilitates fieldbus routing to the upper arm and/or gripper.
- MH50 II-20 also available featuring 20 kg payload; 3,106 mm horizontal reach; 5,585 mm vertical reach and ±0.15 mm repeatability.
- The MH50 II and MH50 II-35 robots can be floor-, wall- or ceilingmounted. Brakes on all axes.
- Mounting for peripheral equipment is provided in multiple locations to make integration easier.
- Both models have an IP67-rated wrist and an IP54-rated body.

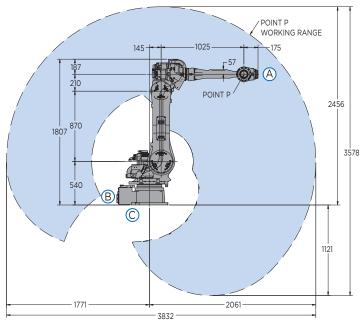
CONTROLLERS

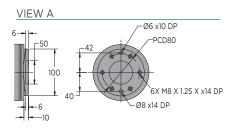




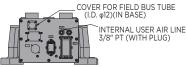
DX200 MLX300*

MH50 II | MH50 II-35 ROBOTS



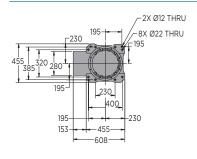


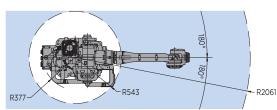
VIEW B



INTERNAL USER I/O CABLE CONNECTOR JL05-2A24-28PC (WITH CAP) MATING CONNECTOR WILL NOT BE SUPPLIED, BUT COMPLETE CABLES ARE AVAILABLE AS AN OPTION

VIEW C





MH50 II robot shown.
All dimensions are metric (mm) and for reference only.
Request detailed drawings for all design/engineering requirements.

SPECIFICATIONS: MH50 II MH50 II-35											
Axes	Maximum motion range		Maximum speed		Allowable moment		Allowable moment of inertia [kg•m²]		Controlled axes	MH50 II 6	MH50 II-35 6
	[°]		[°/sec.]		[N•m]				Maximum payload [kg]	50	35
	MH50 II	MH50 II-35	MH50 II	MH50 II-35	MH50 II	MH50 II-35	MH50 II	MH50 II-35	Repeatability [mm]	±0.07	±0.07
S	±180	±180	180	180	-	-	-	-	Horizontal reach [mm]	2,061	2,538
1	+135/-90	+135/-90	178	140	_	_	_	_	Vertical reach [mm]	3,578	4,448
_	100/ 00	100/ 00	170	140					Weight [kg]	550	570
U	., .	,	178	178	-	-	-	-	Power requirements	3-phase; 240/480/575 VAC at 50/60 Hz	3-phase; 240/480/575
R	±360	±360	250	250	216	147	28	10	Power rating [kVA]	4.0	4.0
В	±125	±125	250	250	216	147	28	10	Internal I/O cable [conductors w/ ground]	24	24
Т	±360	±360	360	360	147	78	11	4	Internal air line [connections]	(1) 3/8"	(1) 3/8"

^{*} The MLX300 software option is not available for use with arc or spot welding, coating, dispensing, cutting or other "path control" applications.

MLX300 fieldbus cards, I/O cards and vision equipment must be purchased separately from the supplier. All peripherals are programmed using a PLC.

OPTIONS

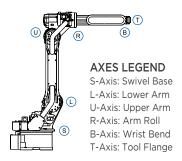
Extended length manipulator cables Robot risers and base plates

External axis kits

Wide variety of fieldbus cards

Vision systems

Robot base and upper arm I/O cables



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