

Release Note

Release Date: July 2018

Product Ver.: Civil 2019 (v1.1)



DESIGN OF CIVIL STRUCTURES

Enhancements

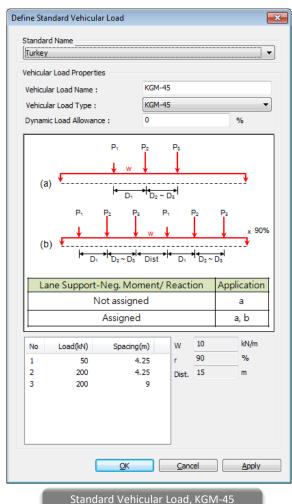
Analysis & Design

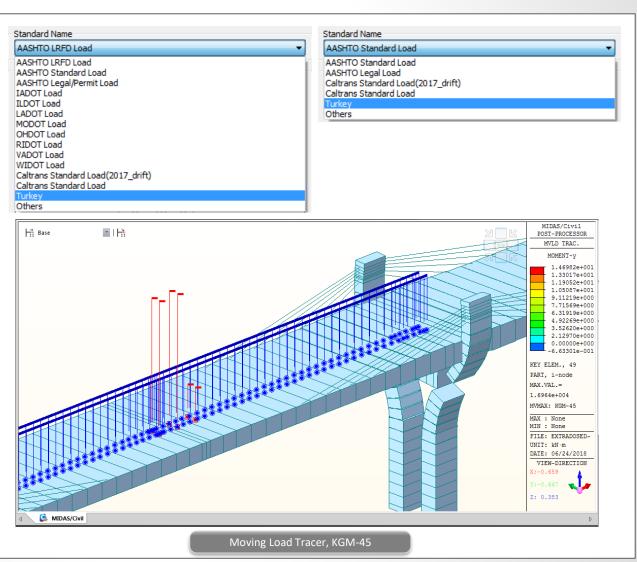
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1. Traffic Load Models for Turkey

- Five Turkish live load models are implemented in midas Civil. KGM-45, H30-S24, H30-S24L, H20-S16, H20-S16L
- These vehicles can be found from the AASHTO LRFD / AASHTO Standard code.

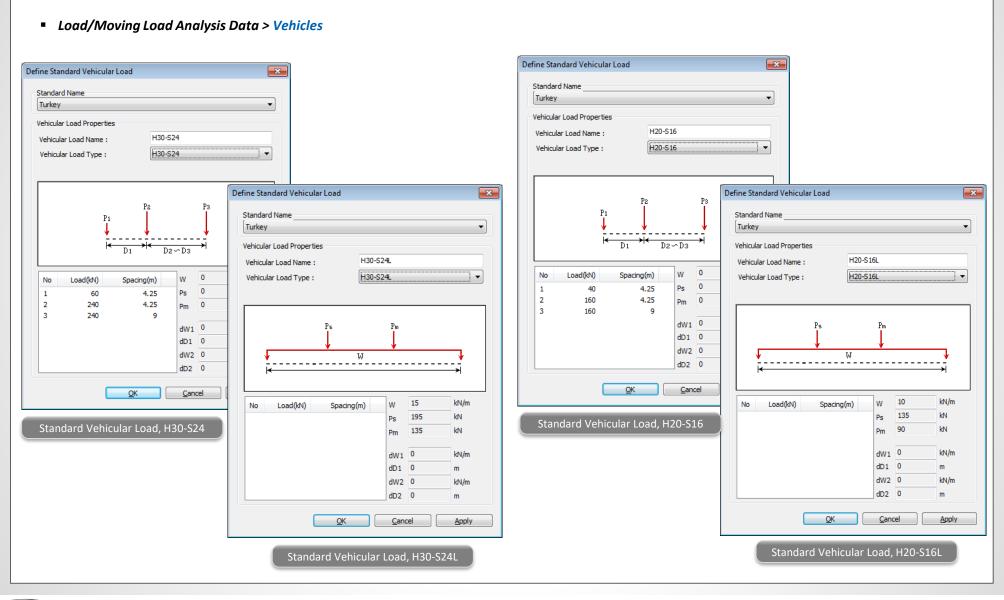








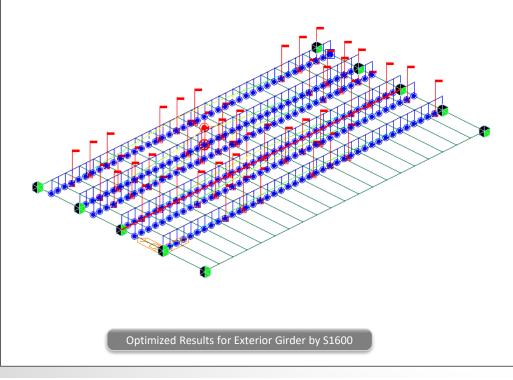
1. Traffic Load Models for Turkey

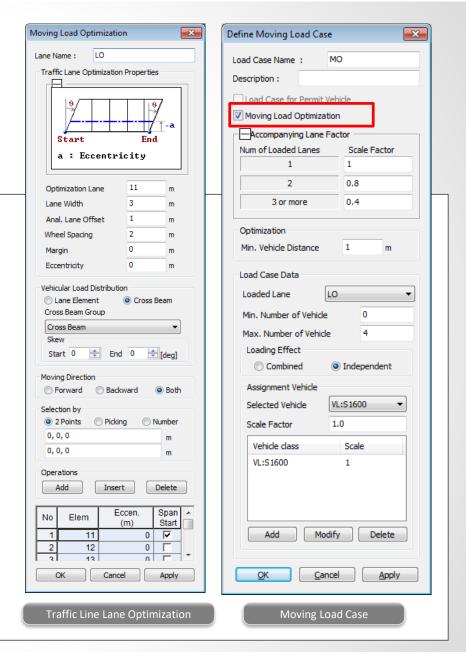




2. Moving Load Optimization for Australia

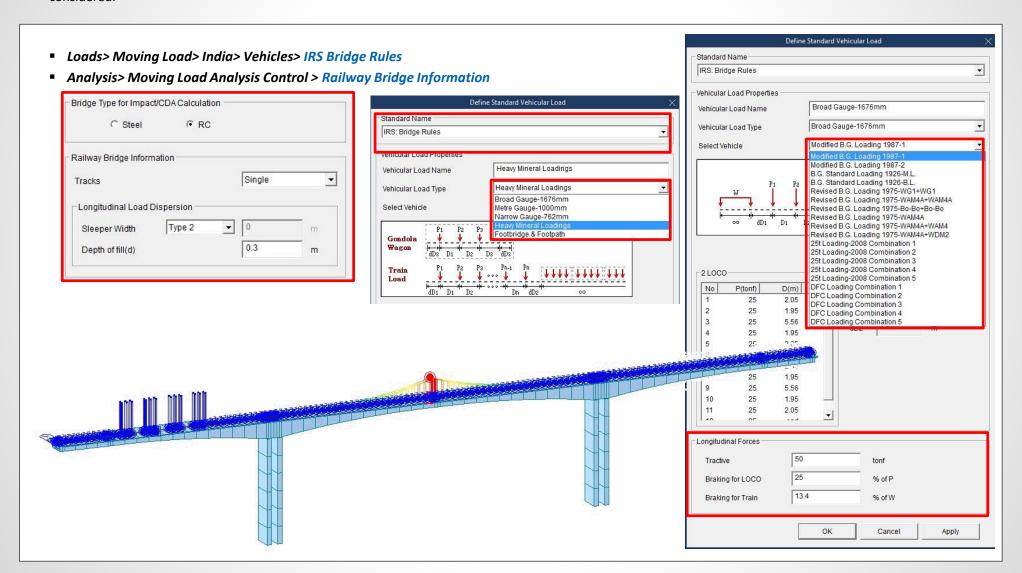
- Now, the moving load optimization function can be applied with the Australia code as well.
- Moving Load Optimization extends the capabilities of moving load analysis and helps to significantly simplify the evaluation of critical vehicle locations. The critical locations of vehicles can be identified in the transverse direction as well as longitudinal direction according to the code provision.
- Load > Moving Load > Traffic Line/Surface Lane > Moving Load Optimization
- Load > Moving Load > Moving Load Cases





3. India IRS Bridge Rules: Railway Loads

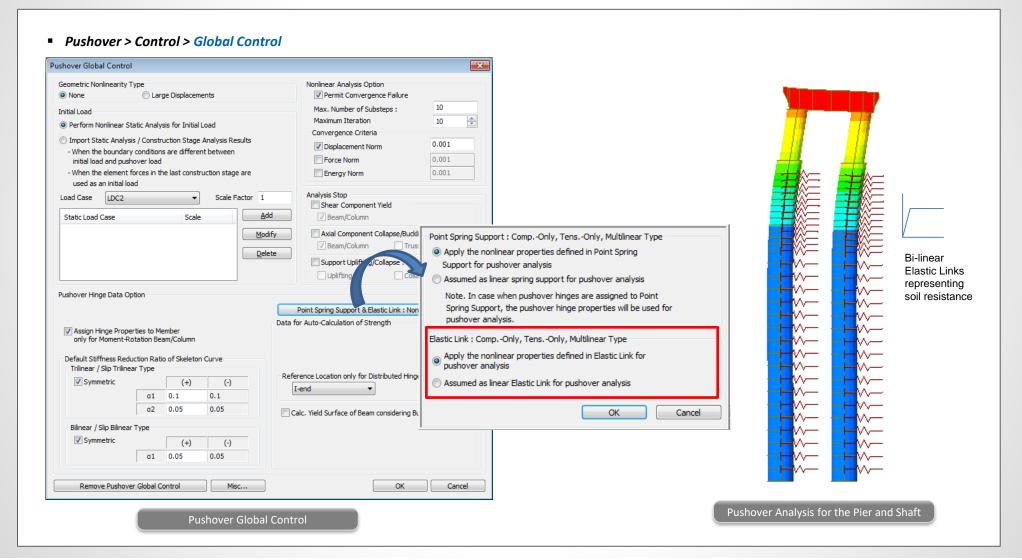
• All the applicable railway loads could now directly be applied to any structure. The tractive and braking load of locomotive as well as wagon would be automatically considered.





4. Nonlinear Elastic Links for Pushover Analysis

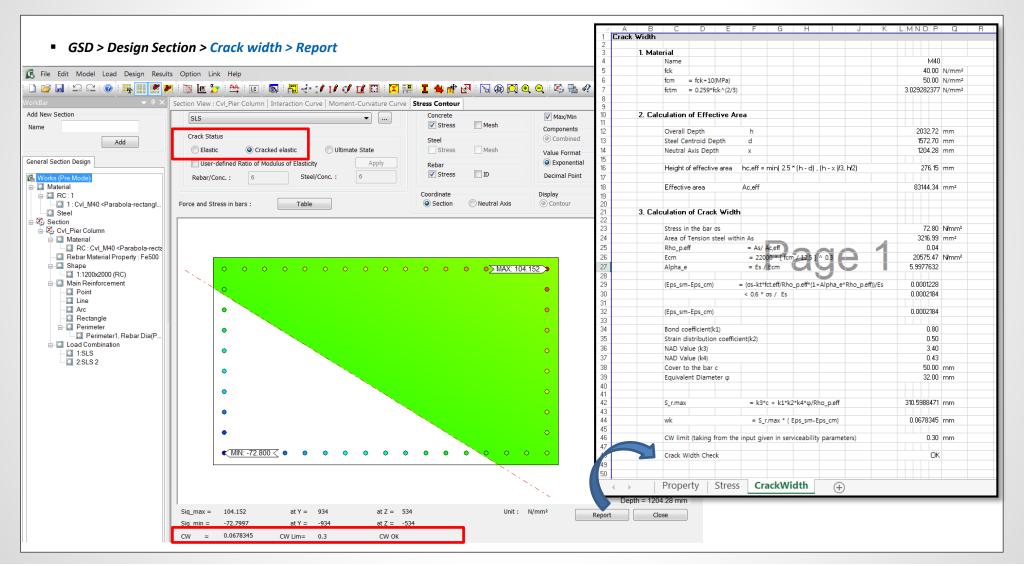
- Nonlinear behavior of the elastic links, i.e. comp.-only, tens.-only, multi-linear can be taken into account in the pushover analysis.
- Link forces imported from static analysis or construction stage analysis cannot be specified as initial loads for pushover analysis.





5. GSD - Crack Width Calculation as per IRC 112: 2011

- For any irregular section, both elastic and cracked-elastic crack width can be computed as per IRC 112: 2011 code.
- Excel report of the stress and crack width calculation can be obtained.

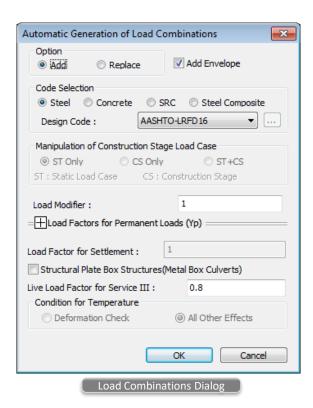




6. AASHTO LRFD 2016 update

Load Combination

	DC									Us	e One o	of These	at a Ti	me
Load Combination	DD DW EH EV ES EL PS CR	LL IM CE BR PL												
Limit State	SH	LS	WA	WS	WL	FR	TU	TG	SE	EQ	BL	IC	CT	CV
Strength I (unless noted)	γ_p	1.75	1.00	_	_	1.00	0.50/1.20	ΥTG	ΥSE	_	_	_	_	
Strength II	γ_p	1.35	1.00	_	_	1.00	0.50/1.20	γ_{TG}	γ_{SE}	_		_		_
Strength III	γ_p	_	1.00	1.0 1.40	_	1.00	0.50/1.20	γτG	γse	_	_	_		_
Strength IV	γ_p	_	1.00	_	_	1.00	0.50/1.20	_	_	_	_	_	_	_
Strength V	γ_p	1.35	1.00	1.0 0.40	1.00	1.00	0.50/1.20	γτG	γse	_	_	_	_	_
Extreme Event I	1.0	γeq	1.00	_	_	1.00	_	_	_	1.00	_	_	_	_
Extreme Event II	γ_p	0.50	1.00	_	_	1.00	_	_	_	_	1.00	1.00	1.00	1.00
Service I	1.00	1.00	1.00	1.0 0.30	1.00	1.00	1.00/1.20	γτG	ΥSE	_	_	_	_	_
Service II	1.00	1.30	1.00	_	_	1.00	1.00/1.20	_	_		_	_	_	_
Service III	1.00	γ_{LL}	1.00	_	_	1.00	1.00/1.20	γτG	γse	_	_	_	_	_
Service IV	1.00	_	1.00	1.0 0.70	_	1.00	1.00/1.20		1.00	_	_	_	_	
Fatigue I— LL, IM & CE only	_	1.50	_	_	_	_		_	_	_	_	_		_
Fatigue II— LL, IM & CE only	_	0.75	_	_	_	_	_	_	_	_	_	_	_	

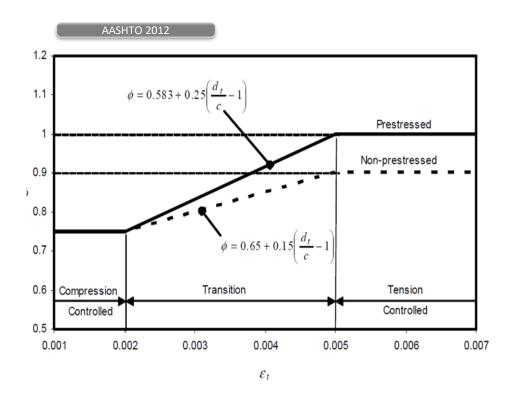


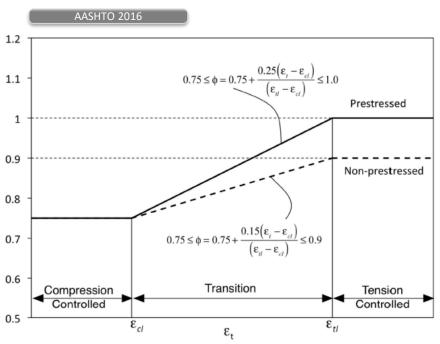
- Load factors of WS for Strength III, Strength V, Service I, Service IV are changed from 1.4 to 1.0, 0.4 to 1.0, 0.3 to 1.0, 0.7 to 1.0, respectively.
- Load factor of permanent effects for Extreme Event I is changed from γ_D to 1.0. AASHTO-LRFD 2012 used a value for γ_D greater than 1.0.



6. AASHTO LRFD 2016 update

Resistance Factor

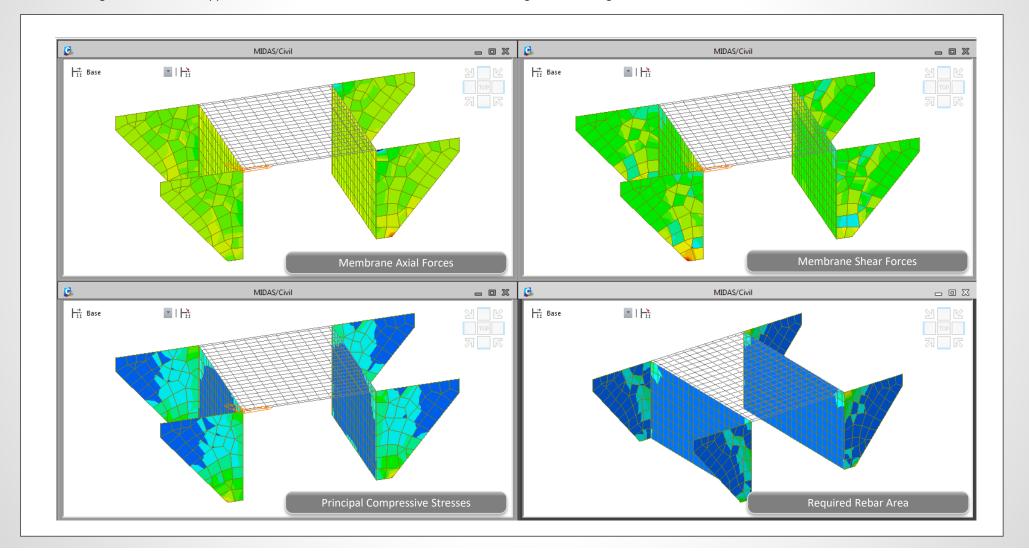




- \bullet ϵ_{cl} : compression-controlled strain limit in the extreme tension steel
- ${\color{blue}\bullet}~\epsilon_{\it tl}$: tension-controlled strain limit in the extreme tension steel

7. Shell Design

- The design of reinforcement concrete shells as per Annex LL of EN 1992-2 is implemented.
- Shell design considers three membrane forces, two flexural moments, twisting moment and two transverse shear forces.
- This design feature can be applied to concrete shell structure, abutment walls / wing walls, under ground structures.

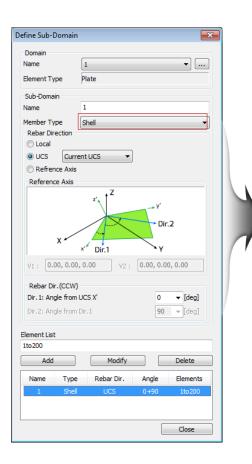




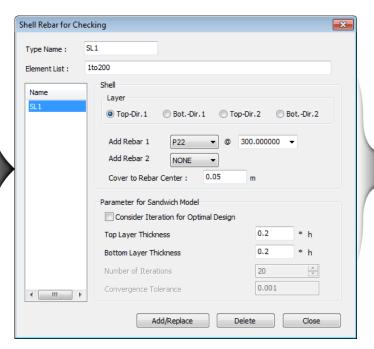
7. Shell Design

Shell Design

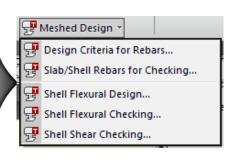
Step 1. Define as a shell member



Step 2. Define Rebar Data and Layer Thickness



Step 3. Run Shell Design and Checking



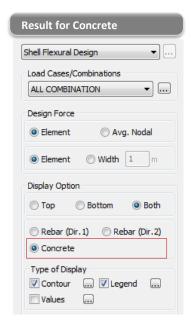
7. Shell Design

Shell Flexural Design/Checking



The followings can be displayed.

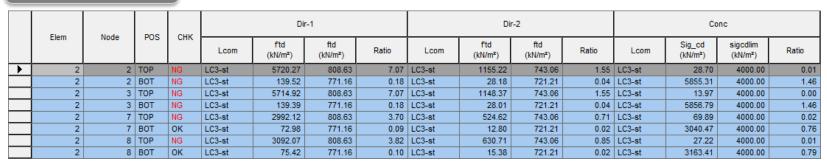
- 1. Membrane Axial Force
- 2. Membrane Shear Force
- 3. Rebar Stress
- 4. As_req (Required reinforcement area)
- S. Rho_req (Required reinforcement ratio)
- 6. Rebar Arrangement



The followings can be displayed.

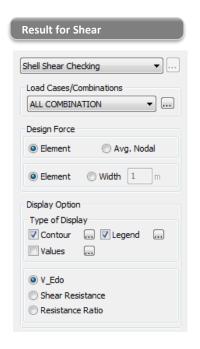
- 1. Membrane Axial Force
- 2. Membrane Shear Force
- 3. Principal Compressive Stress of Concrete

Results Table





Shell Shear Checking



The followings can be displayed.

- V_Edo
 Shear Resistance for Concrete
- 3. Resistance Ratio

Results Table

	Elem	Sub-Domain	Lcom	Node	СНК	Shear Force				Resistance		
						V_Edx (kN/m)	V_Edy (kN/m)	V_Edo (kN/m)	phi_o	V_Rdc (kN/m)	V_Rds (kN/m)	Asw/s (m^2/m)
	2	L-B	LC2-ser	7	ок	-44.70	1.76	44.73	-0.04	117.78	0.00	0.00
	2	L-B	LC2-ser	8	ОК	-43.10	1.76	43.14	-0.04	117.78	0.00	0.00
	2	L-B	LC2-ser	3	OK	-43.10	0.00	43.10	-0.00	126.37	0.00	0.00
	2	L-B	LC2-ser	2	ОК	-44.70	0.00	44.70	-0.00	126.37	0.00	0.00



7. Shell Design

Design Concept of Shell Design

- Shell or plate element subjected to membrane forces Nx,Ny,Nxy + flexural forces Mx,My,Mxy
- Resisted by resultant tensile forces of reinforcement + resultant compressive forces of concrete

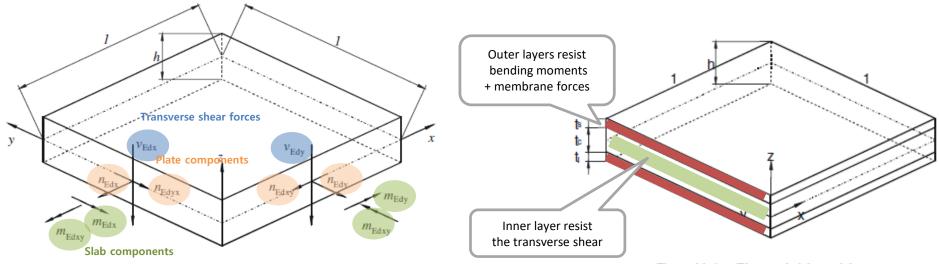
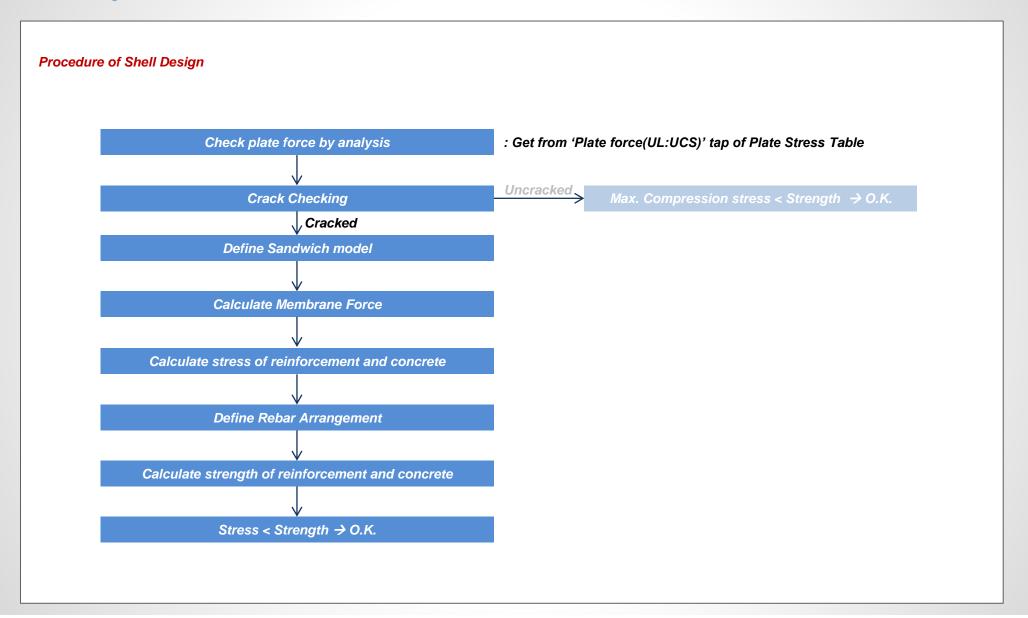


Figure LL.2 — The sandwich model

7. Shell Design





7. Shell Design

Procedure of Shell Design

Crack Checking

$$\Phi = \alpha \frac{J_2}{f_{\rm cm}^2} + \lambda \frac{\sqrt{J_2}}{f_{\rm cm}} + \beta \frac{I_1}{f_{\rm cm}} - 1 \le 0 \qquad \Rightarrow \textit{Uncracked,} \qquad \textit{If } \Phi > \textit{0.0, Cracked}$$

where:

$$J_2 = \frac{1}{6} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]$$

$$J_3 = (\sigma_1 - \sigma_m) (\sigma_2 - \sigma_m) (\sigma_3 - \sigma_m)$$

$$I_1 = \sigma_1 + \sigma_2 + \sigma_3$$

$$\sigma_{\rm m} = (\sigma_1 + \sigma_2 + \sigma_3)/3$$

$$\alpha = \frac{1}{9 k^{1.4}}$$

$$\sigma 1 = Max. [\sigma x, \sigma y] = Max. [Fxx, Fyy]$$

$$\sigma 2 = Min. [\sigma x, \sigma y] = Min. [Fxx, Fyy]$$

$$\sigma 3 = 0$$

$$J_{2} = \frac{1}{6} \left[(\sigma_{1} - \sigma_{2})^{2} + (\sigma_{2} - \sigma_{3})^{2} + (\sigma_{3} - \sigma_{1})^{2} \right] \qquad \lambda = c_{1} \cos \left[\frac{1}{3} \arcsin(C_{2} \cos 3\theta) \right] \qquad \text{for } \cos 3\theta \ge 0$$

$$J_{3} = (\sigma_{1} - \sigma_{w}) (\sigma_{2} - \sigma_{w}) (\sigma_{3} - \sigma_{w}) \qquad \lambda = c_{1} \cos \left[\frac{\pi}{3} - \frac{1}{3} \arccos(-C_{2} \cos 3\theta) \right] \qquad \text{for } \cos 3\theta < 0$$

$$\beta = \frac{1}{3.7k^{1.1}}$$

$$\cos 3\theta = \frac{3\sqrt{3}}{2} \frac{J_3}{J_2^{3/2}}$$

$$c_1 = \frac{1}{0.7k^{0.9}}$$

$$c_2 = 1 - 6.8 (k - 0.07)^2$$

$$k = \frac{f_{\rm ctm}}{f_{\rm cm}}$$

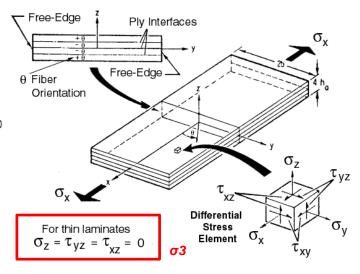


Plate Stress (UL: UCS) Table

	Elem	Load	Node	Fxx (kN/m)	Fyy (kN/m)	Fxy (kN/m)	Fmax (kN/m)	Fmin (kN/m)
ightharpoonup	218	cLCB1	Cent	-17.633	-1.408	-0.083	-1.408	-17.634
	218	cLCB1	186	-18.198	-0.873	-0.319	-0.867	-18.203
	218	cLCB1	238	-17.152	-0.873	-0.275	-0.869	-17.157
	218	cLCB1	185	-17.152	-1.860	0.152	-1.859	-17.154
	218	cLCB1	150	-18.198	-1.860	0.108	-1.859	-18.198
Plate Force(L) \(\) Plate Force(G) \(\) Plate Force(UL:Local) \(\) \(\) Plate Force(UL:UCS) \(\) \(\)								

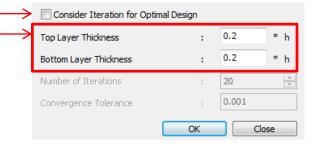


Procedure of Shell Design

Define Sandwich model

Use ' 0.2*h' as default value.

• If check on "Consider Iteration for optimal design", layer thickness will be calculated automatically.



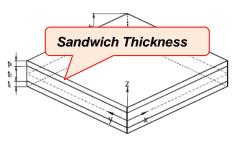


Figure LL.2 — The sandwich model

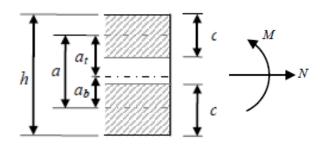
Calculate Membrane Force

• The geometry of sandwich element has to be known to compute the membrane forces (Nxk, Nyk, Nxyk).

$$N_{xt} = N_x \frac{a_b}{a} - \frac{M_x}{a} \qquad N_{xb} = N_x \frac{a_t}{a} + \frac{M_x}{a}$$

$$N_{yt} = N_y \frac{a_b}{a} - \frac{M_y}{a} \qquad N_{yb} = N_y \frac{a_t}{a} + \frac{M_y}{a}$$

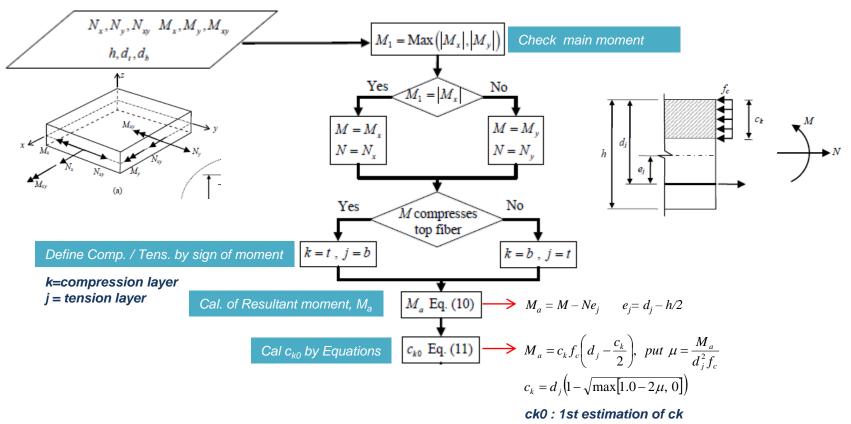
$$N_{xyt} = N_{xy} \frac{a_b}{a} - \frac{M_{xy}}{a} \qquad N_{xyb} = N_{xy} \frac{a_t}{a} + \frac{M_{xy}}{a}$$



7. Shell Design

Procedure of Shell Design

Calculation of Sandwich Thickness for Optimal Design - 1

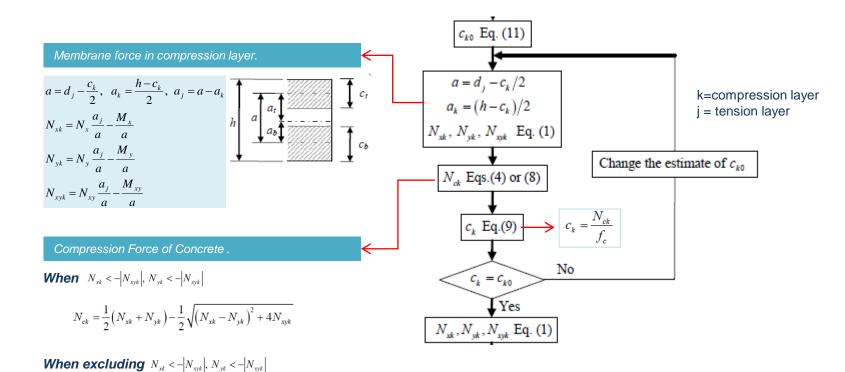


ck: the depth of the compression block

Procedure of Shell Design

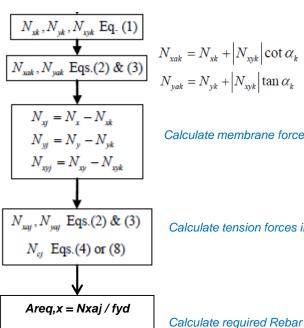
Calculation of Sandwich Thickness for Optimal Design - 2

 $N_{ck} = N_{xyk} \left[(\tan \alpha_k + \cot \alpha_k) \right]$



Procedure of Shell Design

Calculation of Membrane Force in tension layer and Required Rebar Area



Areq,y = Nyaj / fyd

$$N_{xak} = N_{xk} + \left| N_{xyk} \right| \cot \alpha_k$$

$$N_{xak} = N_{xk} + \left| N_{xyk} \right| \cot \alpha_k$$

Calculate Comp. forces in reinforcement in compressed layer. In Gen, Ignore Comp. forces in reinforcement (Required rebar Area by comp. is 0)

Calculate membrane force in tensioned layer.

Calculate tension forces in reinforcement in tension layer.

Calculate required Rebar Area in tension layer.

Procedure of Shell Design

Calculate Force of reinforcement(Tension Layer) and concrete(Compression Layer)

 N_{xak} , N_{vak} : tension forces in reinforcement placed in x and y direction in layer k

N_{ck}: Concrete compression force in layer k

7. Shell Design

Procedure of Shell Design

Modification of Tension force by considering the location of rebar

Distance from center section to center of outerRebar

 $z_{ya} = \frac{N_{ya}z_{yat} + N_{yat}z_{yab}}{\sum N_{ya}} = \frac{168.71 \cdot 67 + 229.47(-80)}{398.18} = -17.72 \ mm$

The actual positions of y reinforcement in top and bottom layer are $z_{yat}^* = 53 \text{ mm}$ and

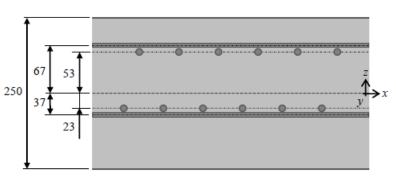
 $z_{yab}^* = -23 \text{ mm}$, the corresponding tension forces at those levels, N_{yat}^* and N_{yab}^* , can be

obtained from:

$$N^*_{yat} = \sum N_{ya} \frac{z_{ya} - z^*_{yab}}{z^*_{yat} - z^*_{yab}} = 398.18 \frac{-17.72 + 23}{53 + 23} = 27.68 \ N/mm$$

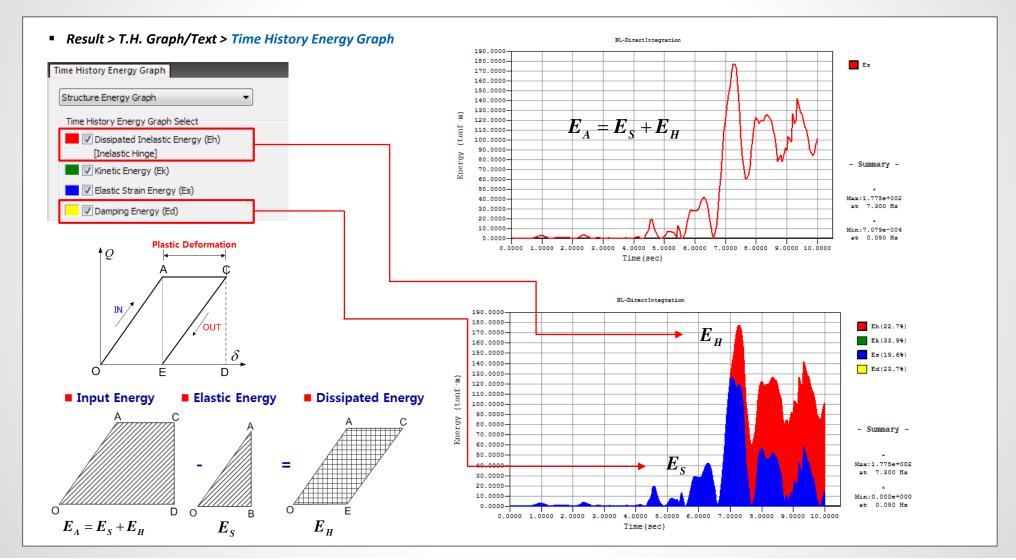
$$N^*_{yab} = \sum N_{ya} \frac{z^*_{yat} - z_{ya}}{z^*_{yat} - z^*_{yab}} = 398.18 \frac{53 + 17.72}{53 + 23} = 370.50 \text{ N/mm}$$

All the measurements in mm



1. Energy Result Graph for Time History Analysis

Print out energy results graph for isolator and vibration control devices in the nonlinear time history analysis.



1. Energy Result Graph for Time History Analysis

Result > T.H. Graph/Text > Time History Energy Graph LD = 1 (DYNA) Time History Energy Graph Eh (9.2%) Structure Energy Graph 4.0000 Ek (6.5%) Es (0.2%) Time History Energy Graph Select Ed (37.4%) Dissipated Inelastic Energy (Eh) Em (9.1%) Ev (0.0%) [Inelastic Hinge] Et (7.0%) Kinetic Energy (Ek) Eo (30.6%) Š Ei(100.0% Elastic Strain Energy (Es) Damping Energy (Ed) - Summary -Maxwell Damper Energy (Em) [Oil Damper] 1.0000 ✓ Velocity Dependent Device Energy (Ev) Max: 4.205e+000 [Viscous | Viscoelastic Damper] at 9,100 Hz Strain Dependent Device Energy (Et) Min:0.000e+000 0.00001.00002.00003.00004.00005.00006.00007.00008.00009.00000.00000 [Elas. + Inel.] [Steel | Hyst. Isolator] Time(sec) ■ Isolator Device Energy (Eo) LD = 1 (DYNA) Plastic Strain Energy (Ep) [Plastic Material (Plate)] 100.0000 Eh (9.2%) 95.0000 Ek (6.5%) Input Energy (Ei) 90.0000 Es (0.2%) 85.0000 Ed (37.4%) 80.0000 Type of Display Em (9.1%) 75.0000 Ev (0.0%) 70.0000-✓ Cumulative Value Type Et (7.0%) 65,0000 Eo (30.6%) 60.0000 Percentage Ei(100.0% 55.0000-50.0000 45.0000 Time History Load Case 40.0000 - Summary -35.0000 30,0000 25.0000 Display Options 20.0000-15.0000 Max:1.000e+002 No Fill Solid Fill at 9.100 Hz 10.0000 5.0000 Min:0.000e+000 Percentage Text Result 0.00001.00002.00003.00004.00005.00006.00007.00008.00009.0000.00000 at 0.010 Hz Time (sec)

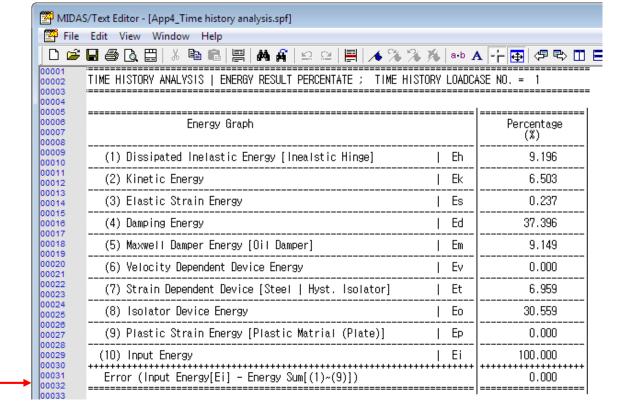


1. Energy Result Graph for Time History Analysis

Result > T.H. Graph/Text > Time History Energy Graph

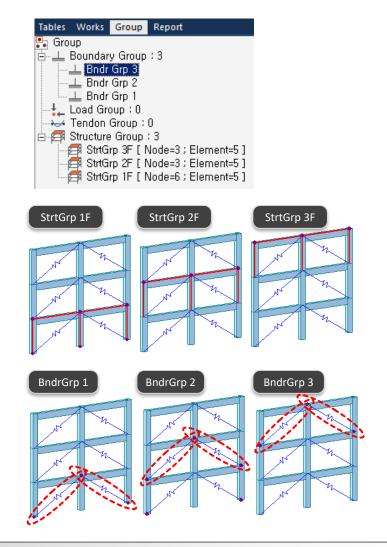


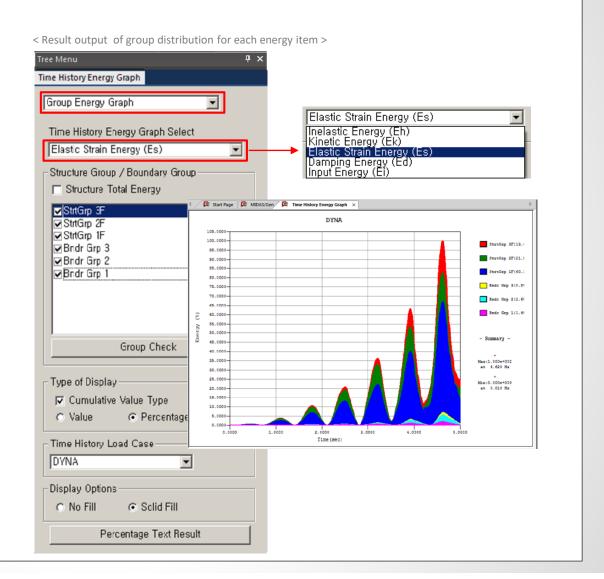
< Text result of the each energy ratio >



1. Energy Result Graph for Time History Analysis

Result > T.H. Graph/Text > Time History Energy Graph

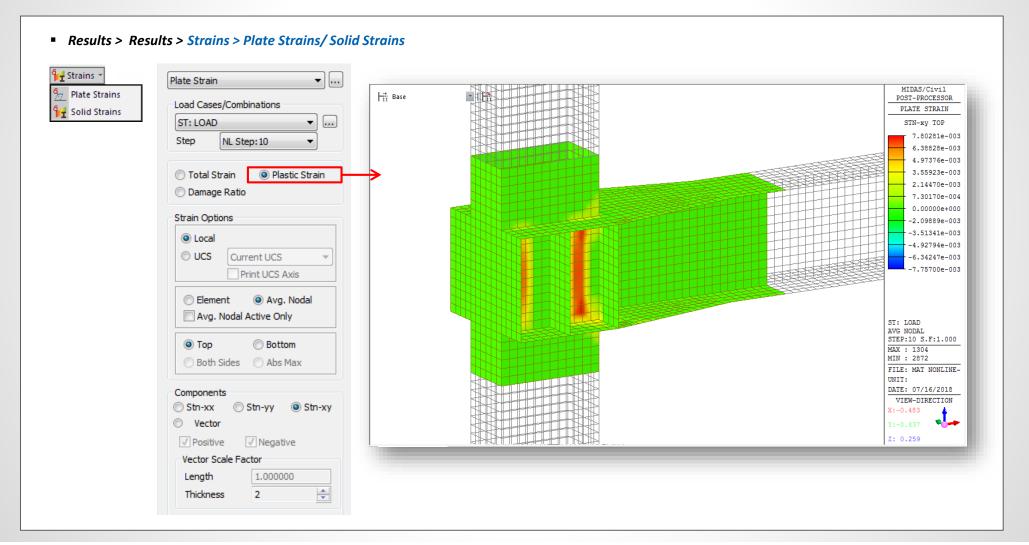






2. Strain Output for Material Nonlinear Analysis

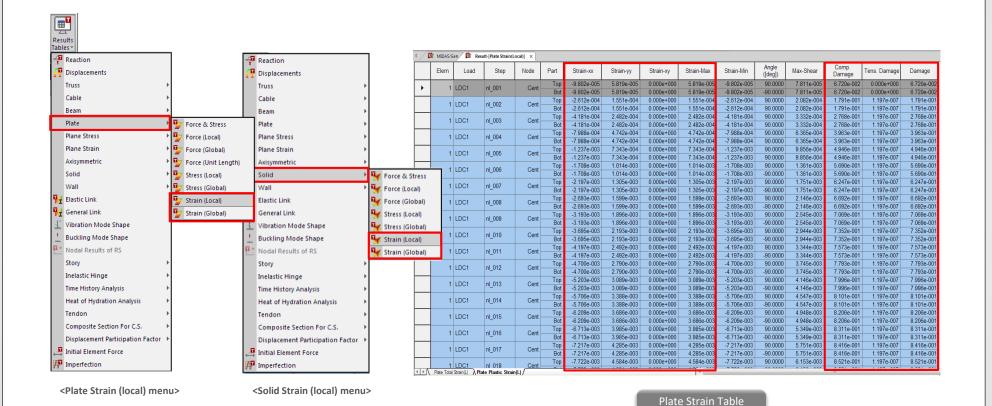
- Strain results are provided for plastic materials, i.e. Tresca, Von Mises, Mohr-Coulomb, Drucker-Prager, and Concrete Damage.
- Damage ratios for compression and tension are provided for the 'Concrete Damage' model.





2. Strain Output for Material Nonlinear Analysis

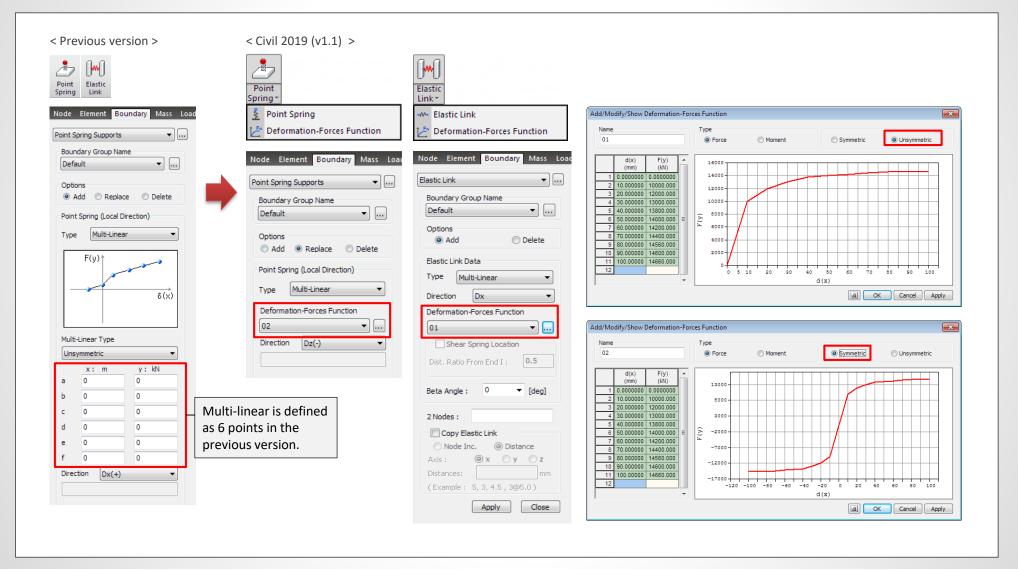
Results > Tables > Results Tables > Plate/ Solid > Strain(local)/ Strain(Global)





3. Multi-linear force-deformation function for Point Spring Support and Elastic Link

• Multi-linear curve for Point Spring Support and Elastic Link can be defined as a function without limitation in terms of number of data.

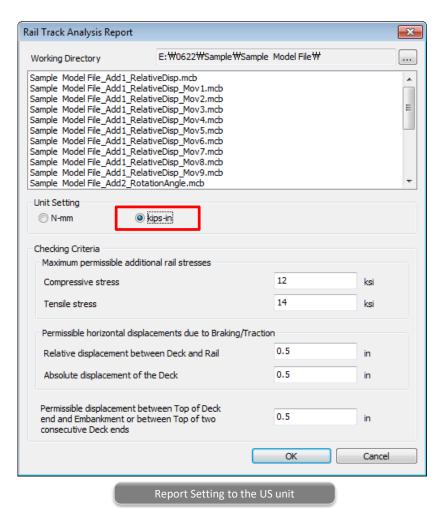


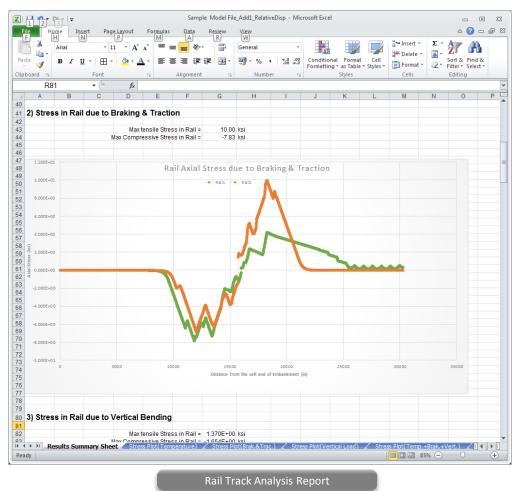


4. Rail Track Analysis Report with the US Unit Setting

Rail Track Analysis report supports the US unit system as well as SI unit system.

Structure > Wizard > Rail Track Analysis Model > Rail Track Analysis Report







5. Data Interface with GTS NX

Reactions from Point Spring Support can be exported to GTS NX.

Export Nodal Results

Target Nodes

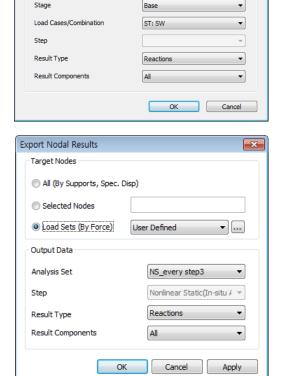
Selected Nodes

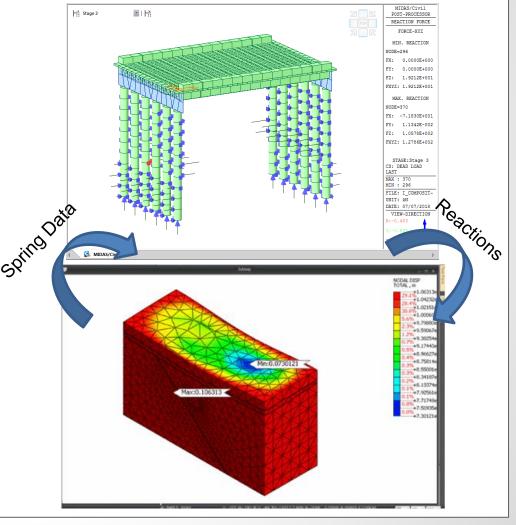
Select Load Case & Direction

All (By Supports, Point Spring, Spec. Disp.)

- Force-displacement results of soil can be imported from GTS NX into midas Civil, and the input data of the multi-linear Point Spring Supports are updated.
 - File > Export > Nodal Results for GTS
 - File > Import > Nodal Results for GTS



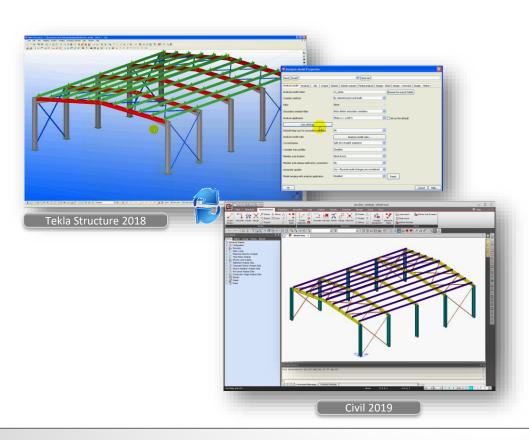






6. Tekla Structure 2018 Interface

- Tekla Structures interface is a tool provided to speed up the entire modeling, analysis, and design procedure of a structure by direct data transfer with midas Civil.
- Data transfer is limited to structural elements.
- Tekla Structure interface enables us to directly transfer a Tekla model data to midas Civil, and delivery back to the Tekla model file. midas Civil text file (*.mct) is used for the roundtrip.
 - File > Import > midas Civil MCT File
 - File > Export > midas Civil MCT File



Category	Features	Tekla <> Gen
	concrete	<>
MATERIAL	steel	<>
IVIATERIAL	pre cast - wood and other types	<> <
	Material user defined	<>
	vertical column	<>
	inclined column	<>
ELEMENT TYPE/	straight beam	<>
ROTATIONS	curved beam	>
	Slab	<>
	vertical panel	>
2D ELEMENTS	Concrete panels and slab	<>
	support	>
BOUNDARY CONDITIONS	beam end release	<>
	section offset	>
	self weigth	>
STATIC LOAD	linear load (uniform or trapezoidal)	<>
	new element	<>
MERGE OPTION	new element that divide other elements	<>
	topology changes	<>

