## YASKAWA

# GP12 Efficient, High-Speed Robot

#### Key Benefits

Highest payload, speeds and wrist allowable moment in its class

Space-efficient design

Engineered for easy installation, operation and maintenance

### Specifications

12 kg payload 1,440 mm horizontal reach 2,511 mm vertical reach ±0.06 mm repeatability

#### Applications

Assembly Material Handling Packaging

#### Controller

YRC1000 YRC1000micro



- Increase your productivity with the fast and efficient GP12 robot.
- All axis speeds have been increased by up to 15% - surpassing other robots in its class.
- Reduced interference design allows close proximity placement of robots.
- Maximum reduction of acceleration/ deceleration times for all robot positions.
- Hollow arm structure eliminates cable interference.
- Highest wrist allowable moment for accurate and repeatable handling.
- Higher payload allows wider range of tooling integration such as double gripper for multi-handling operations.
- Single power and control cable reduces wiring time and increases work efficiency.
- New robot harness design for improved diagnostics and maintenance.

- Home position data can be saved without battery connection for easy maintenance.
- Ideal for high-volume assembly, handling and packaging applications.
- NSF-H1 certified food-grade lubricant option available for food or consumer product packaging environments.
- The GP12 has an IP67-rated wrist and an IP54 body standard. An XP (eXtra Protection) package that increases the body protection rating to IP65 is available.
- The GP12 can be floor-, wall-, tiltor ceiling-mounted. Brakes are included on all axes.
- The GP12 robot is available with either the standard teach pendant or the Smart Pendant.

### GP12 Robot

188

185.5





#### SPECIFICATIONS

Axes	Maximum motion range [°]	Maximum speed [°/sec.]	Allowable moment [N•m]	Allowable moment of inertia [kg•m²]
S	±170	260	-	-
L	+155/-90	230	-	-
U	+150/-85	260	-	-
R	±200	470	22	0.65
В	±150	470	22	0.65
Т	±455	700	9.8	0.17

Specifications for GP12 with XP package may be different.

Internal user I/O connector type is

JL05-2A20-29SC

(provided users)

(with cap). Matching connector type is JL05-6A20-29P

Mounting Options: Floor, Wall, Tilt or Ceiling

\* The MLX300 software option is not available for use with arc or spot welding applications. MLX300 fieldbus cards, I/O cards and vision equipment must be purchased separately from the supplier. All peripherals are programmed using a PLC.

\*\* Food grade grease version includes (2) 3/8" internal user air line connections.

#### Options

- Robot risers and base plates
- MotoSight<sup>™</sup> 2D and 3D vision systems
- PLC integration via MLX300 software option\*

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VIEW A 4 dia(1hole) 22.5° 050 Depth:6mm 62 dia Ø100 VIEW B Internal User Air Line Rc3/8 with pipe plug(A) ¢° /Internal user wiring connector type is JL05-2A20-29PC (with cap) Matching connector type is JL05-6A20-29S (provided users) VIEW C 18 dia through 300 holes,(4 holes) 240 132 260 60 000 16 dia through 100 102 12 dia through holes,(2 holes) 153 hole,(1hole) VIEW D

Tapped holes M6 (2holes) Depth:12mm 130 165 2

All dimensions are metric (mm) and for reference only. Request detailed drawings for all design/engineering requirements.

Item	GP12			
Controlled axes	6			
Maximum payload [kg]	12			
Repeatability [mm]	±0.06			
Horizontal reach [mm]	1,440			
Vertical reach [mm]	2,511			
Weight [kg]	150			
Internal user I/O cable	17 conductors (+ ground)			
Internal user air line	(1) 3/8" connection**			
Power requirements YRC1000 YRC1000micro	Three-phase 380-480 VAC 50/60 Hz Three-phase 200-230 VAC 50/60 Hz			
Power rating [kVA]	1.5			



AXES LEGEND S-Axis: Swivel Base L-Axis: Lower Arm U-Axis: Upper Arm R-Axis: Arm Roll B-Axis: Wrist Bend T-Axis: Tool Flange

**B** 

