



- Inputs for **coordinate system**:
- “**Global**” (default)
 - “**ID** (“1”, “2”, etc.) for local coordinate systems

Quick RBE Springs

RBE Bodies: Spring1

Spring stiffness:

Coord. System ID	Global
Dx	1e08 N/mm
Dy	1e08 N/mm
Dz	0 N/mm
Rx	0 N*mm/rad
Ry	0 N*mm/rad
Rz	500 N*mm/rad
Parametric	<input checked="" type="checkbox"/>

Apply OK Cancel

- RBE bodies to convert**
- RBE names are used for connectors;
 - If RBE are merged, springs will be grouped accordingly

Spring Stiffnesses
Parametric option will use SimLab parameters

Translational Stiffness:

X, X \$DxStiff

Y, Y \$DyStiff

Z, Z \$DzStiff

Rotational Stiffness:

X, X \$RxStiff

Y, Y \$RyStiff

Z, Z \$RzStiff