

Fly when you can, Drive when you must.

The YellowScan Fly & Drive LiDAR solution is a versatile land vehicle-mounted or UAV-mounted mobile mapping system.

It combines high resolution laser scanning and accurate positioning to collect georeferenced point clouds for a wide range of applications.

Key features

- Multi-purpose mobile (ground) and UAV (airborne) mapping system
- Precision positioning using high end GNSS and IMU coupled system
- Easy to use, lightweight, and low power consumption
- Installation on a wide variety of UAVs and vehicles with roofbars



Integrations

- Multi-rotor UAV
- VTOL UAV
- Land vehicle

System integration options.

LiDAR unit

LiDAR system (1)	Surveyor Ultra
Scanner	Hesai XT32M
Precision (2)(4)	2 cm
Accuracy (3) (4)	3 cm
Scanner field of view	360°
Typical range	Up to 100m
Shots per second	640 000
Typical driving speed	Up to 90km/h

IMU / GNSS

GNSS-Inertial solution	SBG Quanta Micro
Multiconstellation	GPS, GLONASS, GALILEO, BEIDOU
Dual dynamic model	Airborne / Mobile mapping
Antenna	GNSS L1/L2 survey grade

- (1) For more information about each LiDAR system, please refer to their respective datasheets.
- (2) Precision, also called reproducibility or repeatability, accounts for the variation in successive measurements taken on the same target.

 (3) Accuracy is the degree of conformity of a measured position to its actual (true) value.
- (4) Post-processed solution, without GNSS outage.

General specifications

Weight: Airborne config.	1.18 kg battery included
Weight: Mobile config.	5.6 kg battery included
Dimension: Airborne config.	L 160 x W 105 x H 140 mm
Dimension: Mobile config.	L 574 x W 315 x H 443 mm



Package configuration.



Urban area with few canyoning GNSS

Open air

Ideally suited for mobile scanning scenario in open air area.



②

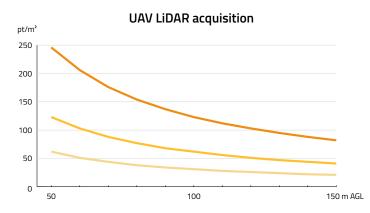
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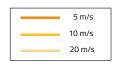
Canyon

Optimized for urban area with canyoning GNSS critical signal.

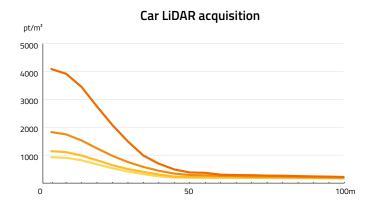
DRIVE PACKAGE	OPEN AIR	CANYON
DAR unit		
Surveyor Ultra		Ø
JAV & vehicle add-ons		
Universal Mounting bracket	Ø	Ø
Odometer (DMI)	Option	Ø
Roofbars adaptor for Fly & Drive POD	Ø	Ø
LiveStation	②	⊘
Software included CloudStation Essential		⊘
Terrasolid TerraScan	⊘	
Terrasolid TerraMatch	⊘	⊘
Qinertia Pro (GUI)	⊘	⊘
LiDAR Quanta Micro firmware		Ø
Typical scenarios		
Basic open area mobile scanning	②	⊘
Stop and Go (traffic lights)	⊘	⊘
Tunnels (GNSS denied areas) by car	×	Up to 100m

Typical mission parameters.





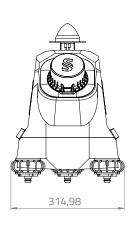
	50 m	100 m	150 m
5 m/s	246	123	82
10 m/s	123	62	41
20 m/s	62	31	21

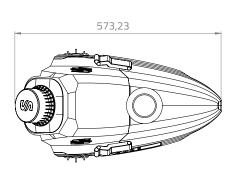


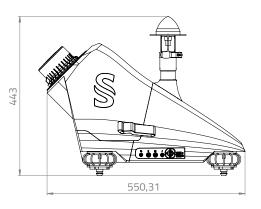


	5 m	10 m	20 m
30 km/h	1489	367	302
50 km/h	754	280	260
70 km/h	503	218	212
90 km/h	232	189	187

Dimensional drawings.







① Dimensions expressed in millimeters

