TactileGlove
Real-World Hand Interactions and Grasp Force Assessment
INTRODUCTION AND PRODUCT OVERVIEW

The TactileGlove with 65 embedded tactile sensing elements throughout the palm and fingers allow natural and accurate measurement of pressures applied to and exerted by the hand. Nearly any hand interaction and operation can be quantified accurately with the TactileGlove. Wireless and battery powered, the TactileGlove is the only pressure measurement glove on the market that enables natural task completion. High-resolution pressure mapping on the hand allow researchers to understand hand interactions and ergonomics to prevent work related injuries and to design better products.

The accompanying Chameleon Software captures and records live data to provide both numeric and visual representation of pressures on the hand.

KEY BENEFITS

+ Accurate measurement of pressure exerted by the human hand
+ Produces quantifiable measures of comfort or safety
+ Allows testing in natural environments without restriction of cables
+ Provides real-time feedback during design processes
+ Provides the comfort of regular gloves
The TactileGlove empowers designers, engineers, medical professionals and scientists to improve products and heighten human performance through scientific and visual feedback as the human hand interacts with the environment.

### KEY FEATURES
- High spatial resolution
- High dynamic pressure range
- Covers critical areas from palm to fingers
- BLE Wireless
- Low-profile and lightweight
- Conformable, does not impede hand full range of motion

### APPLICATIONS

#### Manufacturing Safety & Workers’ Comp Assessment:
- Understanding work activities to prevent injury
- Grasp force required to use power tools
- Grasp force required for fine motor activities such as using dental tools
- Determining if tool modification reduces effort required
- Quantifying hand strength for return-to-work assessments

#### Product Ergonomic Design:
- Quantify what forces people use naturally
- Determining upper and lower limits of forces generated by the hand
- Quantify effort to use tools for human factors & ergonomic designs
- Correlate “feel” of a product in response to controlled design changes
- Understand hand interactions with competitive products
SYSTEM COMPONENTS

1 TactileGlove Pair
2 BLE Module and Housing
3 BLE USB Dongle
4 USB Charging Cable

SENSOR MODELS AND METRICS

**Sensor Characteristics & Performance**

<table>
<thead>
<tr>
<th>Sensing Elements</th>
<th>65</th>
</tr>
</thead>
<tbody>
<tr>
<td>Full Scale Range</td>
<td>80 psi (55 N/cm²)</td>
</tr>
<tr>
<td>Maximum Force</td>
<td>Thumb &amp; Finger tips - 70 N</td>
</tr>
<tr>
<td></td>
<td>Pinky tips - 28 N</td>
</tr>
<tr>
<td>Thickness</td>
<td>~ 2.6 mm</td>
</tr>
<tr>
<td>Signal-to-Noise (SNR)</td>
<td>&gt; 500:1</td>
</tr>
<tr>
<td>Gain Non-Repeatability</td>
<td>&lt; 3%</td>
</tr>
<tr>
<td>Linearity</td>
<td>&gt; 98%</td>
</tr>
<tr>
<td>Minimum Sensitivity</td>
<td>0.04 N</td>
</tr>
</tbody>
</table>

**Electronic Specifications**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
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<tbody>
<tr>
<td>Scan Rate</td>
<td>25 - 40 Hz</td>
</tr>
<tr>
<td>Interconnection</td>
<td>Wireless BlueTooth Low Energy (BLE) - minimum 5 m range</td>
</tr>
<tr>
<td>Battery Life</td>
<td>&gt; 2 hours</td>
</tr>
<tr>
<td>Operating Temperature</td>
<td>0 - 50 °C</td>
</tr>
</tbody>
</table>

1 Performance numbers are for typical system response.

INSIDE VIEW

Sixty-five (65) sensing elements embedded within the glove enable pressure mapping across the most important areas of the hand.
**SIZING CHART**

<table>
<thead>
<tr>
<th>Size</th>
<th>Circumference (around Knuckles)</th>
<th>Hand Length</th>
</tr>
</thead>
<tbody>
<tr>
<td>Small</td>
<td>17.3 - 18.8 cm (6.8 - 7.4 in)</td>
<td>17.4 - 18.4 cm (6.8 - 7.2 in)</td>
</tr>
<tr>
<td>Medium</td>
<td>18.8 - 20.3 cm (7.4 - 8.0 in)</td>
<td>18.4 - 19.4 cm (7.2 - 7.6 in)</td>
</tr>
<tr>
<td>Large</td>
<td>20.3 - 21.8 cm (8.0 - 8.6 in)</td>
<td>19.4 - 20.4 cm (7.6 - 8.0 in)</td>
</tr>
<tr>
<td>X-Large</td>
<td>21.8 - 23.5 cm (8.6 - 9.3 in)</td>
<td>20.4 - 21.5 cm (8.0 - 8.5 in)</td>
</tr>
</tbody>
</table>

**FAQs**

1. **What is the minimum force sensitivity and mass that the TactileGlove can detect?**
   The minimum force that each individual TactileGlove Fingertip Element (38 mm²) can detect is 0.04 N.

2. **Is the TactileGlove waterproof?**
   No, the TactileGlove is not waterproof.

3. **Does the TactileGlove stretch to accommodate variations in hand size and shape?**
   The four sizes are carefully designed to cover hand sizes across a broad spectrum. Please choose the correct size based on your hand dimensions.

4. **Does the TactileGlove measure pressure or force?**
   TactileGlove is calibrated in units of pressure (i.e., psi or N/cm²). Force values are calculated using the known area of the sensor element.

5. **Can the TactileGlove detect fast impact loads?**
   We do not recommend using the TactileGlove for impact applications.

6. **How often does the TactileGlove require calibration?**
   The capacitive based sensing modality of PPS sensors results in an extremely stable sensor with superior repeatability. With proper use and care, the TactileGlove should retain its calibration for years.

**CONTACT US**

For sales inquiries, please visit: pps.us/contact

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